

# **A Gauge Theory on the Anti-de Sitter Space**

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# A Gauge Theory on the Anti-de Sitter Space\*

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## Abstract

We discuss the gauge theory on anti-de Sitter space which has the Levi-Civita connection.

In §1 we review and study a gauge transformation group on which preserves the Levi-Civita connection.

In §2 we define the gauge field (i.e., gauge potential and field strength) and derivative whose field has the space-component and a new (time-component) factor.

In §3 we lead the equation which is satisfied by the gauge field (c.f. Yang-Mills' theory)

In §4 we apply the theorem in the proceeding section to the gauge group  $sl(2, \mathbb{C})$ , and lead the approximate form of Newton's equation of motion under the universal gravitation from the gravitational potential.

## §1. Introduction

We consider an extended Hopf fiber bundle<sup>6)</sup>

$$\begin{array}{ccc} & S^7(\mathbb{C}) = \left\{ \begin{pmatrix} X \\ Y \end{pmatrix} \in M_2(\mathbb{C})^2 / |X| + |Y| = 1 \right\} & \\ \mu_{\pm 1} \nearrow & \downarrow \pi & \text{where } |X|, |Y| \text{ are determinant of } X \text{ and } Y. \\ \longleftarrow & S^4(\mathbb{C}) = S^7(\mathbb{C})/SL(2, \mathbb{C}) & \end{array}$$

and another fiber bundle<sup>6)</sup> which is constructed from view point of the group theory. And we also call the latter an extended Hopf fiber bundle, i.e.,

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$$\begin{array}{ccc}
& \text{Sp}'(2, \mathbb{C}) & \text{SO}(2, 3, \mathbb{C}) \\
\mu_{+1} \nearrow & \downarrow \pi & \downarrow \\
\mathbb{C}^4 \rightarrow S^4(\mathbb{C}) = \text{Sp}'(2, \mathbb{C}) / \left\{ \begin{array}{cc} \text{SL}(2, \mathbb{C}) & 0 \\ 0 & \text{SL}(2, \mathbb{C}) \end{array} \right\} & \xrightarrow[\cong (\text{locally})]{} & \text{SO}(2, 3, \mathbb{C}) / \text{SO}(1, 3, \mathbb{C}) \\
& \text{(extended Hopf fiber bundle)} & \text{(associated frame bundle)}
\end{array}$$

where the fiber space  $\text{Sp}'(2, \mathbb{C})$  is

$$\begin{aligned}
\text{Sp}'(2, \mathbb{C}) &= \left\{ g = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in \text{SL}(4, \mathbb{C}) / \tilde{g} \cdot g = E \right\}, \quad \tilde{g} = \begin{pmatrix} a & c \\ \tilde{b} & \tilde{d} \end{pmatrix} \\
&= \left\{ g = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in \text{SL}(4, \mathbb{C}) / \begin{array}{l} \tilde{a}b + \tilde{c}d = 0 \\ |\tilde{a}| + |\tilde{c}| = 1, |\tilde{b}| + |\tilde{d}| = 1 \end{array} \right\}
\end{aligned}$$

and the projection is

$$\pi: \begin{pmatrix} a & b \\ c & d \end{pmatrix} \rightarrow u = bd^{-1} (= -\tilde{a}^{-1}\tilde{c}) \in \mathbb{C}^4 (|u| \neq -1)$$

or

$$\rightarrow u' = \tilde{b}^{-1}\tilde{d} (= -ac^{-1}) = \tilde{u}^{-1} \in \mathbb{C}^4 (|u'| \neq -1)$$

and the structure group is  $\text{SL}(2, \mathbb{C}) \times \text{SL}(2, \mathbb{C})$ .

Moreover the cross sections on  $\mathbb{C}^4 (|u| \neq -1)$  and  $\mathbb{C}^4 (|u'| \neq -1)$  are

$$\begin{aligned}
\mathbb{C}^4 (|u| \neq -1) \ni u &\rightarrow \mu'_{-1}(u) = \begin{pmatrix} (1+|u|)^{-1/2}E & (1+|u|)^{-1/2}u \\ -(1+|u|)^{-1/2}\tilde{u} & (1+|u|)^{-1/2}E \end{pmatrix}, \\
\mathbb{C}^4 (|u'| \neq -1) \ni u' &\rightarrow \mu'_1(u') = \begin{pmatrix} -(1+|u'|)^{-1/2}u' & (1+|u'|)^{-1/2}E \\ (1+|u'|)^{-1/2}E & (1+|u'|)^{-1/2}\tilde{u}' \end{pmatrix}.
\end{aligned}$$

And the canonical connection  $A_{-1}$  on  $\mathbb{C}^4 (|u| \neq -1)$ ,  $A_1$  on  $\mathbb{C}^4 (|u'| \neq -1)$  are as follows:

Let

$$g(u) = \mu'_{-1}(u) = \frac{1}{(1+|u|)^{1/2}} \begin{pmatrix} E & u \\ -\tilde{u} & E \end{pmatrix}$$

then

$$A = g^{-1}dg = \frac{1}{1+|u|} \begin{pmatrix} \text{Im } u d\tilde{u} & du \\ -d\tilde{u} & \text{Im } \tilde{u} du \end{pmatrix}.$$

Therefore

$$A_{-1} = \frac{1}{1+|u|} \begin{pmatrix} \text{Im } u d\tilde{u} & 0 \\ 0 & \text{Im } \tilde{u} du \end{pmatrix}$$

and for the  $g(u') = \mu'_1(u')$ , the connection is

$$A_1 = \frac{1}{1+|u'|} \begin{pmatrix} \text{Im } \tilde{u}' du' & 0 \\ 0 & \text{Im } u' d\tilde{u}' \end{pmatrix}.$$

Moreover these connections correspond to Levi-Civita connection on the associated frame bundle by the following locally isomorphism<sup>6)</sup>

$$\rho: \text{Sp}'(2, \mathbb{C}) \rightarrow \text{SO}(2, 3, \mathbb{C})$$

and

$$\text{SL}(2, \mathbb{C}) \times \text{SL}(2, \mathbb{C}) \rightarrow \text{SO}(1, 3, \mathbb{C}).$$

The transformation group  $\text{Sp}'(2, \mathbb{C})$  which is called a gauge group on the above extended Hopf fiber bundle preserve the canonical connection and therefore we consider the product bundle  $P = S^4(\mathbb{C}) \times \text{Sp}'(2, \mathbb{C})$  and its adjoint bundle  $\text{sp}'(2, \mathbb{C})_P = P \times_{\text{Ad}} \text{sp}'(2, \mathbb{C})$  on  $S^4(\mathbb{C})$  whose fiber is the Lie algebra  $\text{sp}'(2, \mathbb{C})$  of the Lie group  $\text{Sp}'(2, \mathbb{C})$ , i.e.,

$$\begin{aligned} \text{sp}'(2, \mathbb{C}) &= \left\{ X = \begin{pmatrix} A & B \\ C & D \end{pmatrix} \in \text{sl}(4, \mathbb{C}) / \tilde{X} + X = 0 \right\} \\ &= \left\{ X = \begin{pmatrix} A & B \\ -\tilde{B} & D \end{pmatrix} \in \text{sl}(4, \mathbb{C}) / A, D \in \text{sl}(2, \mathbb{C}) \right\} \end{aligned}$$

and this Lie algebra corresponds to the Lie algebra  $\text{so}(2, 3, \mathbb{C})$  of Lie group  $\text{SO}(2, 3, \mathbb{C})$ .

#### Definition 1.

we define a conjugation "=" and a real part of  $\text{SL}(4, \mathbb{C})$  as follows :

Let

$$\begin{aligned} \text{SL}_R(4, \mathbb{C}) &= \left\{ g = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in \text{SL}(4, \mathbb{C}) / {}^t\tilde{g} \cdot J_4 \cdot g = J_4 \right. \\ &\quad \left. (\text{Sp}^*(2, \mathbb{C})^{61}) \right. \\ &= \left\{ g = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in \text{SL}(4, \mathbb{C}) / \begin{matrix} {}^t\tilde{a}\tilde{c} = {}^t\tilde{c}\tilde{a}, {}^t\tilde{b}\tilde{d} = {}^t\tilde{d}\tilde{b} \\ {}^t\tilde{a}\tilde{d} - {}^t\tilde{c}\tilde{b} = E_2 \end{matrix} \right. \\ &\quad \left. \begin{matrix} {}^t(ac^{-1}) = a\tilde{c}^{-1}, {}^t(bd^{-1}) = b\tilde{d}^{-1} \\ \text{or} \\ {}^t(ca^{-1}) = c\tilde{a}^{-1}, {}^t(db^{-1}) = d\tilde{b}^{-1} \end{matrix} \right\} \end{aligned}$$

be a Lie subgroup of  $\text{SL}(4, \mathbb{C})$  and its Lie algebra is

$$\begin{aligned} \text{sl}_R(4, \mathbb{C}) &= \left\{ X = \begin{pmatrix} A & B \\ C & D \end{pmatrix} \in \text{sl}(4, \mathbb{C}) / {}^t\tilde{X} \cdot J_4 + J_4 \cdot X = 0 \right. \\ &\quad \left. (\text{sp}^*(2, \mathbb{C})^{61}) \right. \\ &= \left\{ X = \begin{pmatrix} A & B \\ C & -{}^t\tilde{A} \end{pmatrix} \in \text{sl}(4, \mathbb{C}) / A \in \text{sl}(2, \mathbb{C}), B, C : \text{hermitian} \right\} \end{aligned}$$

these Lie subgroup and Lie subalgebra correspond to the  $\text{SO}(2, 4)$  and  $\text{so}(2, 4)$  respectively under  $\rho$ .

Let the conjugation "=" be

$$\begin{pmatrix} \overline{A} & \overline{B} \\ C & D \end{pmatrix} = \begin{pmatrix} -{}^t\tilde{D} & {}^t\tilde{B} \\ {}^t\tilde{C} & -{}^t\tilde{A} \end{pmatrix} \quad \text{on } \text{sl}(4, \mathbb{C})$$

then

$$\begin{aligned} \text{Re} \begin{pmatrix} A & B \\ C & D \end{pmatrix} &= \frac{1}{2} \left( \begin{pmatrix} A & B \\ C & D \end{pmatrix} + \begin{pmatrix} \overline{A} & \overline{B} \\ C & D \end{pmatrix} \right) = \begin{pmatrix} \frac{1}{2}(A - {}^t\tilde{D}) & \frac{1}{2}(B + {}^t\tilde{B}) \\ \frac{1}{2}(C + {}^t\tilde{C}) & \frac{1}{2}(D - {}^t\tilde{A}) \end{pmatrix} \\ \text{Im} \begin{pmatrix} A & B \\ C & D \end{pmatrix} &= \frac{1}{2} \left( \begin{pmatrix} A & B \\ C & D \end{pmatrix} - \begin{pmatrix} \overline{A} & \overline{B} \\ C & D \end{pmatrix} \right) = \begin{pmatrix} \frac{1}{2}(A + {}^t\tilde{D}) & \frac{1}{2}(B - {}^t\tilde{B}) \\ \frac{1}{2}(C - {}^t\tilde{C}) & \frac{1}{2}(D + {}^t\tilde{A}) \end{pmatrix} \end{aligned}$$

therefore the following relation holds

$$\text{sl}(4, \mathbb{C}) = \text{sl}_R(4, \mathbb{C}) + i \cdot \text{sl}_R(4, \mathbb{C})$$

and this conjugation corresponds the usual one on the Lie algebra  $\text{SO}(2, 4, \mathbb{C})$ .

We restrict  $\text{SL}(4, \mathbb{C})$  and  $\text{sl}(4, \mathbb{C})$  to the Lie subgroup  $\text{Sp}'(2, \mathbb{C})$  and Lie subalgebra  $\text{sp}'(2, \mathbb{C})$

Let

$$\begin{aligned} \frac{\mathrm{Sp}_R'(2, \mathbb{C})}{(\mathrm{Sp}^*_0(2, \mathbb{C})^{61})} &= \frac{\mathrm{Sp}'(2, \mathbb{C}) \cap \mathrm{SL}_R(4, \mathbb{C})}{(\mathrm{Sp}^*(2, \mathbb{C}))} \\ &= \left\{ g = \begin{pmatrix} a & b \\ -{}^t\tilde{b} & {}^t\tilde{a} \end{pmatrix} \in \mathrm{SL}(4, \mathbb{C}) / \tilde{g} \cdot g = E \right\} \end{aligned}$$

and

$$\begin{aligned} \frac{\mathrm{sp}_R'(2, \mathbb{C})}{(\mathrm{sp}^*_0(2, \mathbb{C})^{61})} &= \frac{\mathrm{sp}'(2, \mathbb{C}) \cap \mathrm{sl}_R(4, \mathbb{C})}{(\mathrm{sp}^*(2, \mathbb{C}))} \\ &= \left\{ X = \begin{pmatrix} A & B \\ -\tilde{B} & -{}^t\tilde{A} \end{pmatrix} \in \mathrm{sl}(4, \mathbb{C}) / A \in \mathrm{sl}(2, \mathbb{C}), B \text{ hermitian} \right\} \end{aligned}$$

These Lie subgroup and Lie subalgebra correspond to the  $\mathrm{SO}(2, 3)$  and  $\mathrm{so}(2, 3)$  respectively under  $\rho$  then the conjugation " $=$ " is

$$\begin{pmatrix} \overline{A} & \overline{B} \\ -\tilde{B} & D \end{pmatrix} = \begin{pmatrix} {}^t\tilde{D} & {}^t\tilde{B} \\ -{}^t\tilde{B} & -{}^t\tilde{A} \end{pmatrix} \quad \text{on } \mathrm{sp}'(2, \mathbb{C})$$

and

$$\begin{aligned} \overline{\mathrm{Re}} \begin{pmatrix} A & B \\ -\tilde{B} & D \end{pmatrix} &= \frac{1}{2} \left( \begin{pmatrix} A & B \\ -\tilde{B} & D \end{pmatrix} + \overline{\sigma} \begin{pmatrix} A & B \\ -\tilde{B} & D \end{pmatrix} \right) = \begin{pmatrix} \frac{1}{2}(A - {}^t\tilde{D}) & \frac{1}{2}(B + {}^t\tilde{B}) \\ \frac{1}{2}(-\tilde{B} - {}^t\tilde{B}) & \frac{1}{2}(D - {}^t\tilde{A}) \end{pmatrix} \\ \overline{\mathrm{Im}} \begin{pmatrix} A & B \\ -\tilde{B} & D \end{pmatrix} &= \frac{1}{2} \left( \begin{pmatrix} A & B \\ -\tilde{B} & D \end{pmatrix} - \overline{\sigma} \begin{pmatrix} A & B \\ -\tilde{B} & D \end{pmatrix} \right) = \begin{pmatrix} \frac{1}{2}(A + {}^t\tilde{D}) & \frac{1}{2}(B - {}^t\tilde{B}) \\ \frac{1}{2}(-\tilde{B} + {}^t\tilde{B}) & \frac{1}{2}(D + {}^t\tilde{A}) \end{pmatrix} \end{aligned}$$

therefore the following relation holds

$$\mathrm{sp}(2, \mathbb{C}) = \mathrm{sp}'_R(2, \mathbb{C}) + i \cdot \mathrm{sp}'_R(2, \mathbb{C}).$$

## § 2 The additional and corrected point concerning to the curvature tensor

Example 1. (the case of electromagnetic field)

Let  $A = \phi dt + A_x dx + A_y dy + A_z dz \in u(1)$  be a connection from (i.e., electromagnetic potential) on the Minkowski space, then the curvature of  $A$  is as follows :

Three components of the electric field are

$$E_x = -\partial_t A_x - \partial_x \phi, \quad E_y = -\partial_t A_y - \partial_y \phi, \quad E_z = -\partial_t A_z - \partial_z \phi$$

and three components of the magnetic field are

$$B_x = \partial_z A_y - \partial_y A_z, \quad B_y = \partial_x A_z - \partial_z A_x, \quad B_z = \partial_y A_x - \partial_x A_y$$

and we define a new factor<sup>4)</sup> (i.e., a time-component of the electric and magnetic field) as

$$E_4 = \underbrace{\partial_t \phi + \partial_x A_x + \partial_y A_y + \partial_z A_z}_{\text{wavy line}}$$

$$B_4 = 0.$$

Then we define a potential matrix, a derivative matrix and a curvature matrix as follows :

$$A = \begin{pmatrix} A_1 + A_2 & A_3 + iA_4 \\ A_3 - iA_4 & A_1 - A_2 \end{pmatrix}, \quad D = \begin{pmatrix} \partial/\partial x^1 + \partial/\partial x^2 & \partial/\partial x^3 + i\partial/\partial x^4 \\ \partial/\partial x^3 - i\partial/\partial x^4 & \partial/\partial x^1 - \partial/\partial x^2 \end{pmatrix}$$

$$F = \tilde{D}\tilde{A} = \begin{pmatrix} E_t + iB_t + (E_x + iB_x) & E_y + iB_y + i(E_z + iB_z) \\ E_y + iB_y - i(E_z + iB_z) & E_t + iB_t - (E_x + iB_x) \end{pmatrix}$$

where each  $\tilde{A}$  and  $\tilde{D}$  is a cofactor matrix of  $A$  and  $D$  respectively.

In following example 2, example 3,  $\tilde{A}$  is a cofactor matrix of  $A$ , when we look upon the components  $A_1, A_2, A_3, A_4$  (matrix) as a scalar

and each  $\tilde{\text{Re}} A = \frac{1}{2}(A + \tilde{A})$ ,  $\tilde{\text{Im}} A = \frac{1}{2}(A - \tilde{A})$  is a real part and imaginary part of  $A$  respectively with respect to the conjugation " $=$ ".

Example 2. (the case of  $SL(2, \mathbb{C})$ )

Let  $A = \sum_{i=1}^4 A_i(x) dx^i \in \mathfrak{sl}(2, \mathbb{C})$  (where  $x^1=t, x^2=x, x^3=y, x^4=z$ ) be a connection form.

then the curvature form is

$$F(A) = dA + \frac{1}{2} [A \wedge A] \\ = \frac{1}{2} \sum_{i,j=1}^4 F_{ij}(x) dx^i \wedge dx^j, \quad F_{ij}(x) = -F_{ji}(x)$$

$$\text{where } F_{ij}(x) = \partial_i A_j(x) - \partial_j A_i(x) + [A_i(x), A_j(x)] \quad (i, j=1 \sim 4).$$

Let

$$E_x = -F_{12}, \quad E_y = -F_{13}, \quad E_z = -F_{14} \\ B_x = F_{34}, \quad B_y = F_{42}, \quad B_z = F_{23}$$

and a new factor (a time-component of the curvature) is

$$E_t = \underbrace{\partial_1 A_1(x) + \partial_2 A_2(x) + \partial_3 A_3(x) + \partial_4 A_4(x)}_{B_t=0}$$

Then the curvature matrix is

$$F = \tilde{D}\tilde{A} + \frac{1}{2} [A \cdot \tilde{A}] \\ = \begin{pmatrix} \partial_t - \partial_2 & -\partial_3 - i\partial_4 \\ \partial_3 + i\partial_4 & \partial_t + \partial_2 \end{pmatrix} \begin{pmatrix} A_1 - A_2 & -A_3 - iA_4 \\ -A_3 + iA_4 & A_1 + A_2 \end{pmatrix} + \frac{1}{2} \left( \begin{pmatrix} A_1 + A_2 & A_3 + iA_4 \\ A_3 - iA_4 & A_1 - A_2 \end{pmatrix} \cdot \begin{pmatrix} A_1 - A_2 & -A_3 - iA_4 \\ -A_3 + iA_4 & A_1 + A_2 \end{pmatrix} \right)$$

where  $[A \cdot B]$  is means that the matrix product  $A \cdot B$  and the bracket product between the component is done at the same time

, i.e.,

$$[A \cdot \tilde{A}] = \begin{pmatrix} [A_1, A_1] - [A_2, A_2] - [A_3, A_3] - [A_4, A_4] & -[A_1, A_3] - i[A_2, A_4] + [A_3, A_1] + i[A_4, A_2] \\ -[A_1, A_2] + [A_2, A_1] + i[A_3, A_4] - i[A_4, A_3] & -i[A_1, A_4] - [A_2, A_3] + [A_3, A_2] + i[A_4, A_1] \\ -[A_1, A_3] - i[A_2, A_4] + [A_3, A_1] + i[A_4, A_2] & [A_1, A_1] - [A_2, A_2] - [A_3, A_3] - [A_4, A_4] \\ +i[A_1, A_4] + [A_2, A_3] - [A_3, A_2] - i[A_4, A_1] & +[A_1, A_2] - [A_2, A_1] - i[A_3, A_4] + i[A_4, A_3] \end{pmatrix} \\ = 2 \begin{pmatrix} & -[A_1, A_3] + i[A_4, A_2] \\ -[A_1, A_2] + i[A_3, A_4] & +i(-[A_1, A_4] + i[A_2, A_3]) \\ -[A_1, A_3] + i[A_4, A_2] & \\ +i(-[A_1, A_4] + i[A_2, A_3]) & -[A_1, A_2] + i[A_3, A_4] \end{pmatrix}$$

In Example 1 and 2, we use the conventional curvature and new factor, but in following Example 3, we

adopt the new definition involved the conjugate " $=$ ".

Example 3. (the case of the gauge group  $SP'(2, \mathbb{C})$ )

Let  $A = \sum_{i=1}^4 A_i(x) dx^i \in sp'(2, \mathbb{C})$  (where  $x^1=t, x^2=x, x^3=y, x^4=z$ ) be a connection form,

then the curvature matrix is defined by

$$F = \tilde{D}\tilde{A} + \frac{1}{2} [\bar{A} \cdot \tilde{A}]$$

$$= \begin{pmatrix} \partial_1 - \partial_2 & -\partial_3 - i\partial_4 \\ -\partial_3 + i\partial_4 & \partial_1 + \partial_2 \end{pmatrix} \begin{pmatrix} A_1 - A_2 & -A_3 - iA_4 \\ -A_3 + iA_4 & A_1 + A_2 \end{pmatrix} + \frac{1}{2} \begin{pmatrix} \bar{A}_1 + \bar{A}_2 & \bar{A}_3 + i\bar{A}_4 \\ \bar{A}_3 - i\bar{A}_4 & \bar{A}_1 - \bar{A}_2 \end{pmatrix} \cdot \begin{pmatrix} A_1 - A_2 & -A_3 - iA_4 \\ -A_3 + iA_4 & A_1 + A_2 \end{pmatrix}$$

where

$$[\bar{A} \cdot \tilde{A}] = \begin{pmatrix} [\bar{A}_1, A_1] - [\bar{A}_2, A_2] - [\bar{A}_3, A_3] - [\bar{A}_4, A_4] & -[\bar{A}_1, A_3] - i[\bar{A}_2, A_4] + [\bar{A}_3, A_1] + i[\bar{A}_4, A_2] \\ -[\bar{A}_1, A_2] + [\bar{A}_2, A_1] + i[\bar{A}_3, A_4] - i[\bar{A}_4, A_3] & -i[\bar{A}_1, A_4] - [\bar{A}_2, A_3] + [\bar{A}_3, A_2] + i[\bar{A}_4, A_1] \\ -[\bar{A}_1, A_3] - i[\bar{A}_2, A_4] + [\bar{A}_3, A_1] + i[\bar{A}_4, A_2] & [\bar{A}_1, A_1] - [\bar{A}_2, A_2] - [\bar{A}_3, A_3] - [\bar{A}_4, A_4] \\ +i[\bar{A}_1, A_4] + [\bar{A}_2, A_3] - [\bar{A}_3, A_2] - i[\bar{A}_4, A_1] & +[\bar{A}_1, A_2] - [\bar{A}_2, A_1] - i[\bar{A}_3, A_4] + i[\bar{A}_4, A_3] \end{pmatrix}$$

#### Definition 2.

Let

$A, A'$  be a connection matrix.

We define the action of the covariant derivative  $\tilde{D}+A$  on the affine space of connection as follows :

$$\begin{aligned} (\tilde{D}+A)\tilde{A}' &= (\tilde{D}+A)(\tilde{A} + \tilde{A}' - \tilde{A}) \\ &= (\tilde{D}+A)\tilde{A} + (\tilde{D}+A)(\tilde{A}' - \tilde{A}) \\ &= (\tilde{D}+A)\tilde{A} + (\tilde{D}+A)B \end{aligned}$$

where  $B = \tilde{A}' - \tilde{A}$  is a vector matrix (4-dimensional vector)

and

$$(\tilde{D}+A)\tilde{A} = \tilde{D}\tilde{A} + \frac{1}{2} [\bar{A} \cdot \tilde{A}] = F(A)$$

$$(\tilde{D}+A)\tilde{B} = \tilde{D}\tilde{B} + \frac{1}{2} [\bar{A} \cdot \tilde{B}].$$

Let  $A_t$  be a connection matrix such that  $A_0 = A$ .

then

$$\begin{aligned} F_t &= (\tilde{D}+A)\tilde{A}_t \\ &= (\tilde{D}+A)(\tilde{A} + \tilde{A}_t - \tilde{A}) \\ &= (\tilde{D}+A)\tilde{A} + (\tilde{D}+A)(\tilde{A}_t - \tilde{A}) \\ &= (\tilde{D}\tilde{A} + \frac{1}{2} [\bar{A} \cdot \tilde{A}]) + \tilde{D}(\tilde{A}_t - \tilde{A}) + [\bar{A} \cdot \tilde{A}_t - \tilde{A}] \\ &= (\tilde{D}\tilde{A}_t + \frac{1}{2} [\bar{A} \cdot \tilde{A}_t]) - \frac{1}{2} [\bar{A} \cdot \tilde{A}] \end{aligned}$$

and

$$\frac{d}{dt} \Big|_{t=0} F_t = \tilde{D}\tilde{\alpha} + \frac{1}{2} [\bar{A} \cdot \tilde{\alpha}], \text{ where } \alpha = \frac{d}{dt} \Big|_{t=0} A_t$$

therefore

$$\frac{d}{dt} \Big|_{t=0} (\tilde{F}_t F_t) = \tilde{F} (\tilde{D}\tilde{\alpha} + [\bar{\tilde{A}} \cdot \tilde{\alpha}]) + (\tilde{D}\tilde{\alpha} + [\bar{\tilde{A}} \cdot \tilde{\alpha}]) F.$$

### § 3 The equation of the gauge group

Let  $YM(A) = \int \text{tr}(\tilde{F}\tilde{F}) \, dv$  be a Yang-Mills functional,  
then the following theorem holds.

Theorem 3.

Let  $\alpha = \frac{d}{dt} \Big|_{t=0} A_t$ , and we assume that  $\alpha$  has a compact support.

then

$$\begin{aligned} \frac{d}{dt} \Big|_{t=0} YM(A_t) = & - \int_M \text{Tr} (\alpha \cdot DF(A) + DF(A) \cdot \alpha) \, dv \\ & + \int_M \text{Tr} ([\bar{\tilde{A}} \cdot \tilde{\alpha}] \cdot \tilde{F}(A) + \tilde{F}(A) \cdot [\bar{\tilde{A}} \cdot \tilde{\alpha}]) \, dv. \end{aligned}$$

proof

$$\begin{aligned} & \frac{d}{dt} \Big|_{t=0} YM(A_t) \\ &= \frac{d}{dt} \Big|_{t=0} \int_M \text{Tr} (\tilde{F}_t \cdot F_t) \, dv \\ &= \int_M \text{Tr} ((\tilde{D}\tilde{\alpha} + \bar{\tilde{A}} \cdot \tilde{\alpha}) \cdot F(A) + \tilde{F}(A) \cdot (\tilde{D}\tilde{\alpha} + \bar{\tilde{A}} \cdot \tilde{\alpha})) \, dv \\ &= \text{Tr} \int_M \widetilde{\text{Re}}((\tilde{D}\tilde{\alpha} + \bar{\tilde{A}} \cdot \tilde{\alpha}) \cdot \tilde{F}(A) + \tilde{F}(A) \cdot (\tilde{D}\tilde{\alpha} + \bar{\tilde{A}} \cdot \tilde{\alpha})) \, dv \\ &= - \text{Tr} \int_M \widetilde{\text{Re}}(\alpha \cdot DF(A) + DF(A) \cdot \alpha) \, dv \\ & \quad + \text{Tr} \int_M \widetilde{\text{Re}}([\bar{\tilde{A}} \cdot \tilde{\alpha}] \cdot \tilde{F}(A) + \tilde{F}(A) \cdot [\bar{\tilde{A}} \cdot \tilde{\alpha}]) \, dv \\ &= - \int_M \text{Tr} (\alpha \cdot DF(A) + DF(A) \cdot \alpha) \, dv \\ & \quad + \int_M \text{Tr} ([\bar{\tilde{A}} \cdot \tilde{\alpha}] \cdot \tilde{F}(A) + \tilde{F}(A) \cdot [\bar{\tilde{A}} \cdot \tilde{\alpha}]) \, dv \end{aligned}$$

q.e.d.

Corollary 4.

$DF(A) + [\bar{\tilde{A}} \cdot F(A)] = 0$  is the condition of the Yang-Mills' connection

proof

Let  $\alpha$ ,  $DF$ ,  $A$  (in Theorem 3) be

$$\alpha = \begin{pmatrix} \alpha_t + \alpha_x & \alpha_y + i\alpha_z \\ \alpha_y - i\alpha_z & \alpha_t - \alpha_x \end{pmatrix} \quad DF = \begin{pmatrix} DF_t + DF_x & DF_y + iDF_z \\ DF_y - iDF_z & DF_t - DF_x \end{pmatrix} \quad A = \begin{pmatrix} A_t + A_x & A_y + iA_z \\ A_y - iA_z & A_t - A_x \end{pmatrix}$$

where the component  $\alpha_t, \alpha_x, \alpha_y, \alpha_z, DF_t, DF_x, DF_y, DF_z, A_t, A_x, A_y, A_z \in \text{sp}'(2, \mathbb{C})$ .

Then the first term in Theorem 3 is

$$\begin{aligned} & \alpha \cdot DF(A) + DF(A) \cdot \alpha \\ &= \begin{pmatrix} \alpha_t + \alpha_x & \alpha_y + i\alpha_z \\ \alpha_y - i\alpha_z & \alpha_t - \alpha_x \end{pmatrix} \begin{pmatrix} DF_t + DF_x & DF_y + iDF_z \\ DF_y - iDF_z & DF_t - DF_x \end{pmatrix} \\ & \quad + \begin{pmatrix} DF_t + DF_x & DF_y + iDF_z \\ DF_y - iDF_z & DF_t - DF_x \end{pmatrix} \begin{pmatrix} \alpha_t + \alpha_x & \alpha_y + i\alpha_z \\ \alpha_y - i\alpha_z & \alpha_t - \alpha_x \end{pmatrix} \\ \therefore \text{Tr}(\alpha \cdot DF(A) + DF(A) \cdot \alpha) \\ &= 2 \text{Tr}\{(\alpha_t \cdot DF_t + DF_t \cdot \alpha_t) + (\alpha_x \cdot DF_x + DF_x \cdot \alpha_x) + (\alpha_y \cdot DF_y + DF_y \cdot \alpha_y) + (\alpha_z \cdot DF_z + DF_z \cdot \alpha_z)\}. \end{aligned}$$

And the second term in Theorem 3 is

$$\begin{aligned} & [\bar{A} \cdot \tilde{\alpha}] \\ &= \begin{pmatrix} [\bar{A}_t, \alpha_t] - [\bar{A}_x, \alpha_x] - [\bar{A}_y, \alpha_y] - [\bar{A}_z, \alpha_z] & -[\bar{A}_t, \alpha_y] - i[\bar{A}_x, \alpha_z] + [\bar{A}_y, \alpha_t] + i[\bar{A}_z, \alpha_x] \\ -[\bar{A}_t, \alpha_x] + [\bar{A}_x, \alpha_t] + i[\bar{A}_y, \alpha_z] - i[\bar{A}_z, \alpha_y] & -i[\bar{A}_t, \alpha_z] - [\bar{A}_x, \alpha_y] + [\bar{A}_y, \alpha_x] + i[\bar{A}_z, \alpha_t] \\ -[\bar{A}_t, \alpha_y] - i[\bar{A}_x, \alpha_z] + [\bar{A}_y, \alpha_t] + i[\bar{A}_z, \alpha_x] & [\bar{A}_t, \alpha_t] - [\bar{A}_x, \alpha_x] - [\bar{A}_y, \alpha_y] - [\bar{A}_z, \alpha_z] \\ +i[\bar{A}_t, \alpha_z] + [\bar{A}_x, \alpha_y] - [\bar{A}_y, \alpha_x] - i[\bar{A}_z, \alpha_t] & +[\bar{A}_t, \alpha_x] - [\bar{A}_x, \alpha_t] - i[\bar{A}_y, \alpha_z] + i[\bar{A}_z, \alpha_y] \end{pmatrix} \end{aligned}$$

therefore

$$\begin{aligned} & \text{Tr}([\bar{A} \cdot \tilde{\alpha}] \hat{F}(A) + \hat{F}(A) [\bar{A} \cdot \tilde{\alpha}]) \\ &= 2 \text{Tr}\{([\bar{A}_t, \alpha_t] - [\bar{A}_x, \alpha_x] - [\bar{A}_y, \alpha_y] - [\bar{A}_z, \alpha_z]) \cdot F_t \\ & \quad + F_t \cdot ([\bar{A}_t, \alpha_t] - [\bar{A}_x, \alpha_x] - [\bar{A}_y, \alpha_y] - [\bar{A}_z, \alpha_z]) \\ & \quad + (-[\bar{A}_t, \alpha_x] + [\bar{A}_x, \alpha_t] + i[\bar{A}_y, \alpha_z] - i[\bar{A}_z, \alpha_y]) \cdot (-F_x) \\ & \quad + (-F_x) \cdot (-[\bar{A}_t, \alpha_x] + [\bar{A}_x, \alpha_t] + i[\bar{A}_y, \alpha_z] - i[\bar{A}_z, \alpha_y]) \\ & \quad + (-[\bar{A}_t, \alpha_y] - i[\bar{A}_x, \alpha_z] + [\bar{A}_y, \alpha_t] + i[\bar{A}_z, \alpha_x]) \cdot (-F_y) \\ & \quad + (-F_y) \cdot (-[\bar{A}_t, \alpha_y] - i[\bar{A}_x, \alpha_z] + [\bar{A}_y, \alpha_t] + i[\bar{A}_z, \alpha_x]) \\ & \quad + (-i[\bar{A}_t, \alpha_z] - [\bar{A}_x, \alpha_y] + [\bar{A}_y, \alpha_x] + i[\bar{A}_z, \alpha_t]) \cdot (iF_z) \\ & \quad + (iF_z) \cdot (-i[\bar{A}_t, \alpha_z] - [\bar{A}_x, \alpha_y] + [\bar{A}_y, \alpha_x] + i[\bar{A}_z, \alpha_t])\}. \end{aligned}$$

The coefficient of  $\alpha_t$  (i.e.,  $\alpha_x = \alpha_y = \alpha_z = 0$ ) is as follows:

$$\begin{aligned} & 2 \text{Tr}(-\alpha_t DF_t - DF_t \alpha_t \\ & \quad + [\bar{A}_t, \alpha_t] F_t + F_t [\bar{A}_t, \alpha_t] - [\bar{A}_x, \alpha_t] F_x - F_x [\bar{A}_x, \alpha_t] - [\bar{A}_y, \alpha_t] F_y - F_y [\bar{A}_y, \alpha_t] - [\bar{A}_z, \alpha_t] F_z - F_z [\bar{A}_z, \alpha_t]) \end{aligned}$$

And we calculate the coefficients of following  $\alpha_{12} \sim \alpha_{18}$  and  $\alpha'_{12} \sim \alpha'_{14}$  as follows :

Let

$$\alpha_t = \begin{pmatrix} \alpha_{t2} & \alpha_{t3} + i\alpha_{t4} & \alpha_{t5} + \alpha_{t6} & \alpha_{t7} & \alpha_{t8} \\ \alpha_{t3} - i\alpha_{t4} & -\alpha_{t2} & \alpha_{t7} - i\alpha_{t8} & \alpha_{t5} - \alpha_{t6} & \\ -\alpha_{t5} + \alpha_{t6} & \alpha_{t7} + i\alpha_{t8} & \alpha_{t2}' & \alpha_{t3}' + i\alpha_{t4}' & \\ \alpha_{t7} - i\alpha_{t8} & -\alpha_{t5} - \alpha_{t6} & \alpha_{t3}' - i\alpha_{t4}' & -\alpha_{t2}' & \end{pmatrix}$$

and

$$DF_t = \begin{pmatrix} DF_{t2} & DF_{t3} + DF_{t4} & DF_{t5} + DF_{t6} & DF_{t7} + iDF_{t8} \\ DF_{t3} - iDF_{t4} & -DF_{t2} & DF_{t7} - iDF_{t8} & DF_{t5} - DF_{t6} \\ -DF_{t5} + DF_{t6} & DF_{t7} + iDF_{t8} & DF_{t2}' & DF_{t3}' + iDF_{t4}' \\ DF_{t7} - iDF_{t8} & -DF_{t5} - DF_{t6} & DF_{t3}' - iDF_{t4}' & -DF_{t2}' \end{pmatrix}.$$

then

$$\begin{pmatrix} \alpha_t DF_t + DF_t \alpha_t & \\ & \end{pmatrix} = \begin{pmatrix} 2(\alpha_{t2} DF_{t2} + \alpha_{t3} DF_{t3} + \alpha_{t4} DF_{t4} & (\alpha_{t2} DF_{t6} + \alpha_{t3} DF_{t7} + \alpha_{t4} DF_{t8} \\ \alpha_{t5} DF_{t5} + \alpha_{t6} DF_{t6} + \alpha_{t7} DF_{t7} + \alpha_{t8} DF_{t8}) E & + \alpha_{t6} DF_{t2}' + \alpha_{t7} DF_{t3}' + \alpha_{t8} DF_{t4}' \\ & + DF_{t2} \alpha_{t6} + DF_{t3} \alpha_{t7} + DF_{t4} \alpha_{t8} \\ & + DF_{t6} \alpha_{t2}' + DF_{t7} \alpha_{t3}' + DF_{t8} \alpha_{t4}') E \\ \hline (\alpha_{t6} DF_{t2} + \alpha_{t7} DF_{t3} + \alpha_{t8} DF_{t4} & \\ + \alpha_{t2}' DF_{t6} + \alpha_{t3}' DF_{t7} + \alpha_{t4}' DF_{t8} & \\ + DF_{t6} \alpha_{t2}' + DF_{t7} \alpha_{t3}' + DF_{t8} \alpha_{t4}' & \\ + DF_{t2} \alpha_{t6} + DF_{t3} \alpha_{t7} + DF_{t4} \alpha_{t8}) E & 2(-\alpha_{t6} DF_{t5} + \alpha_{t6} DF_{t6} + \alpha_{t7} DF_{t7} + \alpha_{t8} DF_{t8} \\ & + \alpha_{t2}' DF_{t2}' + \alpha_{t3}' DF_{t3}' + \alpha_{t4}' DF_{t4}') E \end{pmatrix}$$

therefore

$$\begin{aligned} & 2\text{Tr}(\alpha_t DF_t + DF_t \alpha_t) \\ &= 8 \{ \alpha_{t2} DF_{t2} + \alpha_{t3} DF_{t3} + \alpha_{t4} DF_{t4} + \alpha_{t2}' DF_{t2}' + \alpha_{t3}' DF_{t3}' + \alpha_{t4}' DF_{t4}' \\ & \quad - 2(\alpha_{t5} DF_{t5} - \alpha_{t6} DF_{t6} - \alpha_{t7} DF_{t7} - \alpha_{t8} DF_{t8}) \}. \end{aligned}$$

Let

$$A_i = \begin{pmatrix} A_{i2} & A_{i3} + iA_{i4} & A_{i5} + A_{i6} & A_{i7} + iA_{i8} \\ A_{i3} - iA_{i4} & -A_{i2} & A_{i7} - iA_{i8} & A_{i5} - A_{i6} \\ -A_{i5} + A_{i6} & A_{i7} + iA_{i8} & A_{i2}' & A_{i3}' + iA_{i4}' \\ A_{i7} - iA_{i8} & -A_{i5} - A_{i6} & A_{i3}' - iA_{i4}' & -A_{i2}' \end{pmatrix} \quad (i=t, x, y, z)$$

$$\bar{A}_i = \begin{pmatrix} -\bar{A}_{i2}' & -\bar{A}_{i3}' + i\bar{A}_{i4}' & \bar{A}_{i5} + \bar{A}_{i6} & \bar{A}_{i7} - i\bar{A}_{i8} \\ -\bar{A}_{i3}' - i\bar{A}_{i4}' & \bar{A}_{i2}' & \bar{A}_{i7} + i\bar{A}_{i8} & \bar{A}_{i5} - \bar{A}_{i6} \\ -\bar{A}_{i5} + \bar{A}_{i6} & \bar{A}_{i7} - i\bar{A}_{i8} & -\bar{A}_{i2} & -\bar{A}_{i3} + i\bar{A}_{i4} \\ \bar{A}_{i7} + i\bar{A}_{i8} & -\bar{A}_{i5} - \bar{A}_{i6} & -\bar{A}_{i3} - i\bar{A}_{i4} & \bar{A}_{i2} \end{pmatrix}$$

$$F_i = \begin{pmatrix} F_{i2} & F_{i3} + iF_{i4} & F_{i5} + F_{i6} & F_{i7} + iF_{i8} \\ F_{i3} - iF_{i4} & -F_{i2} & F_{i7} - iF_{i8} & F_{i5} - F_{i6} \\ -F_{i5} + F_{i6} & F_{i7} + iF_{i8} & F_{i2}' & F_{i3}' + iF_{i4}' \\ F_{i7} - iF_{i8} & -F_{i5} - F_{i6} & F_{i3}' - iF_{i4}' & -F_{i2}' \end{pmatrix} \quad (i=t, x, y, z)$$

then

$$\begin{aligned} & \text{Tr}([\bar{A}_{11}, \alpha_t] F_t + F_t [\bar{A}_1, \alpha_t]) \quad (i=t, x, y, z) \\ &= 8(i\bar{A}_{13}'\alpha_{t4} + i\bar{A}_{14}'\alpha_{t3} + \bar{A}_{15}\alpha_{t5} - \bar{A}_{16}\alpha_{t5} - i\bar{A}_{17}\alpha_{t8} - i\bar{A}_{18}\alpha_{t7}) F_{12} \\ & \quad + 8(-i\bar{A}_{12}'\alpha_{t4} - i\bar{A}_{14}'\alpha_{t2} + \bar{A}_{15}\alpha_{t7} + i\bar{A}_{16}\alpha_{t8} - \bar{A}_{17}\alpha_{t5} + i\bar{A}_{18}\alpha_{t6}) F_{13} \\ & \quad - 8i(-\bar{A}_{12}'\alpha_{t3} + \bar{A}_{13}'\alpha_{t2} + i\bar{A}_{15}\alpha_{t8} + \bar{A}_{16}\alpha_{t7} - \bar{A}_{17}\alpha_{t6} + i\bar{A}_{18}\alpha_{t5}) F_{14} \\ & \quad - 8((- \bar{A}_{12}'\alpha_{t6} - \bar{A}_{13}'\alpha_{t7} + \bar{A}_{14}'\alpha_{t8}) - (\alpha_{t2}\bar{A}_{16} + \alpha_{t3}\bar{A}_{17} - \alpha_{t4}\bar{A}_{18}) \\ & \quad \quad + (\bar{A}_{16}\alpha_{t2}' + \bar{A}_{17}\alpha_{t3}' - \bar{A}_{18}\alpha_{t4}') - (-\alpha_{t6}\bar{A}_{12} - \alpha_{t7}\bar{A}_{13} + \alpha_{t8}\bar{A}_{14})) F_{15} \end{aligned}$$

$$\begin{aligned}
& + 8 \{ (-\bar{A}_{12}'\alpha_{15} + i\bar{A}_{13}'\alpha_{18} + i\bar{A}_{14}'\alpha_{17}) - (\alpha_{12}\bar{A}_{15} + i\alpha_{13}\bar{A}_{18} + i\alpha_{14}\bar{A}_{17}) \\
& \quad + (\bar{A}_{15}\alpha_{12}' - i\bar{A}_{17}\alpha_{14}' - i\bar{A}_{18}\alpha_{13}') - (-\alpha_{15}\bar{A}_{12} - i\alpha_{17}\bar{A}_{14} - i\alpha_{18}\bar{A}_{13}) \} F_{16} \\
& + 8 \{ (-i\bar{A}_{12}'\alpha_{18} - \bar{A}_{13}'\alpha_{15} - i\bar{A}_{14}'\alpha_{16}) - (-i\alpha_{12}\bar{A}_{18} + \alpha_{13}\bar{A}_{15} - i\alpha_{14}\bar{A}_{16}) \\
& \quad + (\bar{A}_{15}\alpha_{13}' + i\bar{A}_{16}\alpha_{14}' + i\bar{A}_{18}\alpha_{12}') - (-\alpha_{15}\bar{A}_{13} + i\alpha_{16}\bar{A}_{14} + i\alpha_{18}\bar{A}_{12}) \} F_{17} \\
& - 8i \{ (-\bar{A}_{12}'\alpha_{17} + \bar{A}_{13}'\alpha_{16} + i\bar{A}_{14}'\alpha_{15}) - (\alpha_{12}\bar{A}_{17} - \alpha_{13}\bar{A}_{16} + i\alpha_{14}\bar{A}_{15}) \\
& \quad + (i\bar{A}_{15}\alpha_{14}' + \bar{A}_{16}\alpha_{13}' - \bar{A}_{17}\alpha_{12}') - (i\alpha_{15}\bar{A}_{14} - \alpha_{16}\bar{A}_{13} + \alpha_{17}\bar{A}_{12}) \} F_{18} \\
& + 8 \{ (-\bar{A}_{15}\alpha_{16} + \bar{A}_{16}\alpha_{15} - i\bar{A}_{17}\alpha_{18} - i\bar{A}_{18}\alpha_{17} + i\bar{A}_{13}\alpha_{14}' + i\bar{A}_{14}\alpha_{13}') \} F_{12}' \\
& + 8 \{ (-\bar{A}_{15}\alpha_{17} + i\bar{A}_{16}\alpha_{18} + \bar{A}_{17}\alpha_{15} + i\bar{A}_{18}\alpha_{16} - i\bar{A}_{12}\alpha_{14}' - i\bar{A}_{14}\alpha_{12}') \} F_{13}' \\
& - 8i \{ (-i\bar{A}_{15}\alpha_{18} + \bar{A}_{16}\alpha_{17} - \bar{A}_{17}\alpha_{16} - i\bar{A}_{18}\alpha_{15} - \bar{A}_{12}\alpha_{13}' + \bar{A}_{13}\alpha_{12}') \} F_{14}' \\
& = \alpha_{12} (8i(-\bar{A}_{13}'F_{14} - \bar{A}_{14}'F_{13}) + 8(\bar{A}_{16}F_{15} - \bar{A}_{15}F_{16} + i\bar{A}_{18}F_{17} + i\bar{A}_{17}F_{18})) \\
& + \alpha_{13} (-8i(-\bar{A}_{12}'F_{14} - \bar{A}_{14}'F_{12}) + 8(\bar{A}_{17}F_{15} - i\bar{A}_{18}F_{16} - \bar{A}_{15}F_{17} - i\bar{A}_{16}F_{18})) \\
& + \alpha_{14} (8i(-\bar{A}_{12}'F_{13} + \bar{A}_{13}'F_{12}) + 8(-\bar{A}_{18}F_{15} - i\bar{A}_{17}F_{16} + i\bar{A}_{16}F_{17} - \bar{A}_{15}F_{18})) \\
& + \alpha_{15} (8(-\bar{A}_{16}F_{12} - \bar{A}_{17}F_{13} + \bar{A}_{18}F_{14}) + 8(-\bar{A}_{12}'F_{16} + \bar{A}_{12}F_{16} - \bar{A}_{13}'F_{17} + \bar{A}_{13}F_{17} + \bar{A}_{14}'F_{18} - \bar{A}_{14}F_{18}) \\
& \quad + 8(\bar{A}_{16}F_{12}' + \bar{A}_{17}F_{13}' - \bar{A}_{18}F_{14}')) \\
& + \alpha_{16} (8(\bar{A}_{15}F_{12} + i\bar{A}_{18}F_{13} + i\bar{A}_{17}F_{14}) + 8(\bar{A}_{12}'F_{15} - \bar{A}_{12}F_{15} - i\bar{A}_{14}'F_{17} - i\bar{A}_{14}F_{17} - i\bar{A}_{13}'F_{18} - i\bar{A}_{13}F_{18}) \\
& \quad + 8(-\bar{A}_{15}F_{12}' + i\bar{A}_{18}F_{13}' + i\bar{A}_{17}F_{14}')) \\
& + \alpha_{17} (8(-i\bar{A}_{18}F_{12} + \bar{A}_{15}F_{13} - i\bar{A}_{16}F_{14}) + 8(\bar{A}_{13}'F_{15} - \bar{A}_{13}F_{15} + i\bar{A}_{14}'F_{16} + i\bar{A}_{14}F_{16} + i\bar{A}_{12}'F_{18} + i\bar{A}_{12}F_{18}) \\
& \quad + 8(-i\bar{A}_{18}F_{12}' - \bar{A}_{15}F_{13}' - i\bar{A}_{16}F_{14}')) \\
& + \alpha_{18} (8(-i\bar{A}_{17}F_{12} + i\bar{A}_{16}F_{13} + \bar{A}_{15}F_{14}) + 8(-\bar{A}_{14}'F_{15} + \bar{A}_{14}F_{15} + \bar{A}_{13}'F_{16} + i\bar{A}_{13}F_{16} - i\bar{A}_{12}'F_{17} - i\bar{A}_{12}F_{17}) \\
& \quad + 8(-i\bar{A}_{17}F_{12}' + i\bar{A}_{16}F_{13}' - \bar{A}_{15}F_{14}')) \\
& + \alpha_{12}' (8(-\bar{A}_{16}F_{15} + \bar{A}_{15}F_{16} + i\bar{A}_{18}F_{17} + i\bar{A}_{17}F_{18}) + 8i(\bar{A}_{14}F_{13}' + \bar{A}_{13}F_{14}')) \\
& + \alpha_{13}' (8(-\bar{A}_{17}F_{15} - i\bar{A}_{18}F_{16} + \bar{A}_{15}F_{17} - i\bar{A}_{16}F_{18}) - 8i(\bar{A}_{14}F_{12}' + \bar{A}_{12}F_{14}')) \\
& + \alpha_{14}' (8(\bar{A}_{18}F_{15} - i\bar{A}_{17}F_{16} + i\bar{A}_{16}F_{17} + \bar{A}_{15}F_{18}) - 8i(\bar{A}_{13}F_{12}' - \bar{A}_{12}F_{13}')).
\end{aligned}$$

Let  $\varepsilon_i = -1$  and  $\varepsilon_i = 1$  ( $i = x, y, z$ ), then the following formulas hold, because the coefficients of  $\alpha$ 's is all zero, i.e.,

$$\begin{aligned}
\alpha_{12} : DF_2 + \sum_{i=t,x,y,z} 2\varepsilon_i \{ & -i(\bar{A}_{13}'F_{14} + \bar{A}_{14}'F_{13}) + (\bar{A}_{16}F_{15} - \bar{A}_{15}F_{16} + i\bar{A}_{18}F_{17} + i\bar{A}_{17}F_{18}) \} \\
\alpha_{13} : DF_3 + \sum_{i=t,x,y,z} 2\varepsilon_i \{ & i(\bar{A}_{12}'F_{14} + \bar{A}_{14}'F_{12}) + (\bar{A}_{17}F_{15} - i\bar{A}_{18}F_{16} - \bar{A}_{15}F_{17} - i\bar{A}_{16}F_{18}) \} \\
\alpha_{14} : DF_4 + \sum_{i=t,x,y,z} 2\varepsilon_i \{ & -i(\bar{A}_{12}'F_{13} - \bar{A}_{13}'F_{12}) + (-\bar{A}_{18}F_{15} - i\bar{A}_{17}F_{16} + i\bar{A}_{16}F_{17} - \bar{A}_{15}F_{18}) \} \\
\alpha_{15} : -DF_5 + \sum_{i=t,x,y,z} \varepsilon_i \{ & (-\bar{A}_{16}F_{12} - \bar{A}_{17}F_{13} + \bar{A}_{18}F_{14}) + (-\bar{A}_{12}'F_{16} + \bar{A}_{12}F_{16} - \bar{A}_{13}'F_{17} + \bar{A}_{13}F_{17} + \bar{A}_{14}'F_{18} - \bar{A}_{14}F_{18}) \\
& + (\bar{A}_{16}F_{12}' + \bar{A}_{17}F_{13}' - \bar{A}_{18}F_{14}') \} \\
\alpha_{16} : DF_6 + \sum_{i=t,x,y,z} \varepsilon_i \{ & (\bar{A}_{15}F_{12} + i\bar{A}_{18}F_{13} + i\bar{A}_{17}F_{14}) + (\bar{A}_{12}'F_{15} - \bar{A}_{12}F_{15} - i\bar{A}_{14}'F_{17} - i\bar{A}_{14}F_{17} - i\bar{A}_{13}'F_{18} - i\bar{A}_{13}F_{18}) \\
& + (-\bar{A}_{15}F_{12}' + i\bar{A}_{18}F_{13}' + i\bar{A}_{17}F_{14}') \} \\
\alpha_{17} : DF_7 + \sum_{i=t,x,y,z} \varepsilon_i \{ & (-i\bar{A}_{18}F_{12} + \bar{A}_{15}F_{13} - i\bar{A}_{16}F_{14}) + (\bar{A}_{13}'F_{15} - \bar{A}_{13}F_{15} + i\bar{A}_{14}'F_{16} + i\bar{A}_{14}F_{16} + \bar{A}_{12}'F_{18} + i\bar{A}_{12}F_{18}) \\
& + (-i\bar{A}_{18}F_{12}' - \bar{A}_{15}F_{13}' - i\bar{A}_{16}F_{14}') \} \\
\alpha_{18} : DF_8 + \sum_{i=t,x,y,z} \varepsilon_i \{ & (-i\bar{A}_{17}F_{12} + i\bar{A}_{16}F_{13} + \bar{A}_{15}F_{14}) + (-\bar{A}_{14}'F_{15} + \bar{A}_{14}F_{15} + i\bar{A}_{13}'F_{16} + i\bar{A}_{13}F_{16} - i\bar{A}_{12}'F_{17} - i\bar{A}_{12}F_{17}) \\
& + (-i\bar{A}_{17}F_{12}' + i\bar{A}_{16}F_{13}' - \bar{A}_{15}F_{14}') \} \\
\alpha_{12}' : DF_2' + \sum_{i=t,x,y,z} 2\varepsilon_i \{ & (-\bar{A}_{16}F_{15} + \bar{A}_{15}F_{16} + i\bar{A}_{18}F_{17} + i\bar{A}_{17}F_{18}) + i(\bar{A}_{14}F_{13}' + \bar{A}_{13}F_{14}') \} \\
\alpha_{13}' : DF_3' + \sum_{i=t,x,y,z} 2\varepsilon_i \{ & (-\bar{A}_{17}F_{15} - i\bar{A}_{18}F_{16} + \bar{A}_{15}F_{17} - i\bar{A}_{16}F_{18}) - i(\bar{A}_{14}F_{12}' + \bar{A}_{12}F_{14}') \}
\end{aligned}$$

$$\alpha_{t_4}' : DF_4' + \sum_{l=t,x,y,z} 2\varepsilon_l \{ (\bar{A}_{18}F_{15} - i\bar{A}_{17}F_{16} + i\bar{A}_{16}F_{17} + \bar{A}_{15}F_{18}) - i(\bar{A}_{13}F_{12}' - \bar{A}_{12}F_{13}') \}$$

$$\begin{pmatrix} DF_t & 0 \\ 0 & DF_t \end{pmatrix} + \widetilde{\text{Re}} \left( \begin{pmatrix} \bar{\bar{A}}_t - \bar{\bar{A}}_x & -\bar{\bar{A}}_y - i\bar{\bar{A}}_z \\ -\bar{\bar{A}}_y + i\bar{\bar{A}}_z & \bar{\bar{A}}_t + \bar{\bar{A}}_x \end{pmatrix} \cdot \begin{pmatrix} F_t + F_x & F_y + iF_z \\ F_y - iF_z & F_t - F_x \end{pmatrix} \right) = 0.$$

The coefficient of  $\alpha_x$  (i.e.,  $\alpha_t = \alpha_y = \alpha_z = 0$ ) is as follows:

$$2 \text{Tr}(-\alpha_x DF_x - DF_x \alpha_x$$

$$+ [\bar{\bar{A}}_t, \alpha_x] F_t + F_t [\bar{\bar{A}}_t, \alpha_x] - [\bar{\bar{A}}_x, \alpha_x] F_x - F_x [\bar{\bar{A}}_x, \alpha_x] + i[\bar{\bar{A}}_y, \alpha_x] F_y + iF_y [\bar{\bar{A}}_y, \alpha_x] \\ - i[\bar{\bar{A}}_z, \alpha_x] F_z - iF_z [\bar{\bar{A}}_z, \alpha_x])$$

therefore

$$\begin{pmatrix} DF_x & 0 \\ 0 & DF_x \end{pmatrix} + \widetilde{\text{Im}}_x \left( \begin{pmatrix} \bar{\bar{A}}_t - \bar{\bar{A}}_x & -\bar{\bar{A}}_y - i\bar{\bar{A}}_z \\ -\bar{\bar{A}}_y + i\bar{\bar{A}}_z & \bar{\bar{A}}_t + \bar{\bar{A}}_x \end{pmatrix} \cdot \begin{pmatrix} F_t + F_x & F_y + iF_z \\ F_y - iF_z & F_t - F_x \end{pmatrix} \right) = 0.$$

The coefficient of  $\alpha_x$  (i.e.,  $\alpha_t = \alpha_y = \alpha_z = 0$ ) is as follows:

$$2 \text{Tr}(-\alpha_y DF_y - DF_y \alpha_y$$

$$+ [\bar{\bar{A}}_t, \alpha_y] F_t + F_t [\bar{\bar{A}}_t, \alpha_y] - i[\bar{\bar{A}}_x, \alpha_y] F_x - iF_x [\bar{\bar{A}}_x, \alpha_y] - [\bar{\bar{A}}_y, \alpha_y] F_y - F_y [\bar{\bar{A}}_y, \alpha_y] \\ + i[\bar{\bar{A}}_z, \alpha_y] F_z + iF_z [\bar{\bar{A}}_z, \alpha_y])$$

therefore

$$\begin{pmatrix} 0 & DF_y \\ DF_y & 0 \end{pmatrix} + \widetilde{\text{Im}}_y \left( \begin{pmatrix} \bar{\bar{A}}_t - \bar{\bar{A}}_x & -\bar{\bar{A}}_y - i\bar{\bar{A}}_z \\ -\bar{\bar{A}}_y + i\bar{\bar{A}}_z & \bar{\bar{A}}_t + \bar{\bar{A}}_x \end{pmatrix} \cdot \begin{pmatrix} F_t + F_x & F_y + iF_z \\ F_y - iF_z & F_t - F_x \end{pmatrix} \right) = 0.$$

The coefficient of  $\alpha_z$  (i.e.,  $\alpha_t = \alpha_x = \alpha_y = 0$ ) is as follows:

$$2 \text{Tr}(-\alpha_z DF_z - DF_z \alpha_z$$

$$+ [\bar{\bar{A}}_t, \alpha_z] F_t + F_t [\bar{\bar{A}}_t, \alpha_z] + i[\bar{\bar{A}}_x, \alpha_z] F_x + iF_x [\bar{\bar{A}}_x, \alpha_z] - i[\bar{\bar{A}}_y, \alpha_z] F_y - iF_y [\bar{\bar{A}}_y, \alpha_z] \\ - [\bar{\bar{A}}_z, \alpha_z] F_z - F_z [\bar{\bar{A}}_z, \alpha_z])$$

therefore

$$\begin{pmatrix} 0 & iDF_z \\ -iDF_z & 0 \end{pmatrix} + \widetilde{\text{Im}}_z \left( \begin{pmatrix} \bar{\bar{A}}_t - \bar{\bar{A}}_x & -\bar{\bar{A}}_y - i\bar{\bar{A}}_z \\ -\bar{\bar{A}}_y + i\bar{\bar{A}}_z & \bar{\bar{A}}_t + \bar{\bar{A}}_x \end{pmatrix} \cdot \begin{pmatrix} F_t + F_x & F_y + iF_z \\ F_y - iF_z & F_t - F_x \end{pmatrix} \right) = 0.$$

The above equation are in all

$$DF(A) + [\bar{\bar{A}} \cdot F(A)] = 0.$$

this is the condition of the Yang-Mills' connection.

#### § 4 A example of gravitational field

Let  $(v^0, v^1, v^2, v^3)$  be the 4-dimensional velocity, i.e.,

$$(dc\tau)^2 = (dct)^2 - (dx)^2 - (dy)^2 - (dz)^2$$

and  $v^0 = dct/dc\tau = c/(c^2 - u^2)^{1/2}$ ,

$$v^1 = dx/dc\tau = x_t/(c^2 - u^2)^{1/2}$$

$$v^2 = dy/dc\tau = y_t/(c^2 - u^2)^{1/2}$$

$$v^3 = dz/dc\tau = z_t/(c^2 - u^2)^{1/2}$$

where  $u^2 = (x_t)^2 + (y_t)^2 + (z_t)^2$ .

When a particle has a velocity  $u = (x_t, y_t, z_t) = (x_t, 0, 0)$ , the coordinate transformation in space-time is

$$\begin{pmatrix} ct' \\ x' \\ y' \\ z' \end{pmatrix} = \begin{pmatrix} v^0 ct - v^1 x \\ -v^1 ct + v^0 x \\ y \\ z \end{pmatrix} = \begin{pmatrix} v^0 & -v^1 & 0 & 0 \\ -v^1 & v^0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} ct \\ x \\ y \\ z \end{pmatrix},$$

and this is a Lorentz ( $SO(1,3)$ -) transformation (SPECIAL THEORY OF RELATIVITY).

Therefore we look upon  $u = (x_t, y_t, z_t)$  as a parameter of the Lorentz transformation  $L(u)$ , and when the velocity change as the time going (ACCELERATION), we assign the different transformation  $L(x_t, y_t, z_t)$  at each point on the locus (world line) of the particle.

We correspond this Lorentz group in space-time to the gauge subgroup in extended Hopf fiber bundle as follows<sup>6)</sup>:

The transformation  $SL(2, \mathbb{C})$  on  $M_2(\mathbb{C})^2$  is

$$g = \begin{pmatrix} a & b \\ c & d \end{pmatrix} : \begin{pmatrix} X \\ Y \end{pmatrix} \rightarrow \begin{pmatrix} aX + bY \\ cX + dY \end{pmatrix}.$$

The gauge group  $Sp(2, \mathbb{C})$  preserve the extended Hopf fiber bundle and acts on the base space such as when  $|Y| \neq 0$

$$u = XY^{-1} \rightarrow u' = (aX + bY)(cX + dY)^{-1} \\ = (au + b)(cu + d)^{-1}.$$

Specially when the gauge subgroup  $SL(2, \mathbb{C})' = \begin{pmatrix} a & 0 \\ 0 & \bar{a}^{-1} \end{pmatrix}$ ,  $a \in SL(2, \mathbb{C})$

acts as the Lorentz transformation on the  $R^{1,3}$ (Minkowski space), i.e.,

$$u \rightarrow u' = au(\bar{a}^{-1})^{-1} \\ = au^t \bar{a}$$

$$\text{where we look upon } u = \begin{pmatrix} ct+x & y+iz \\ y-iz & ct-x \end{pmatrix} \text{ as the vector } \begin{pmatrix} ct \\ x \\ y \\ z \end{pmatrix}.$$

By this 2-1 correspondence  $\sigma: SL(2, \mathbb{C})' \rightarrow SO(1,3)$ , we denote the above gauge transformation as  $\pm L'(x_t, y_t, z_t)$ .

and we assign the gauge transformation  $L'(x_t, y_t, z_t)$  at each point on the world line of the particle.

(Does the gauge transformation  $SL(2, \mathbb{C})'$  generate the gravitation ?)

We assign the gauge transformation  $L'(x_t, t, z_t)$  on each point  $(ct, x, y, z)$  of space-time.

Then the potential is

$$\begin{aligned} A &= (L')^{-1} DL' \\ &= (L')^{-1} (d_{ct}(L') d_{ct} + d_x(L') dx + d_y(L') dy + d_z(L') dz) \\ &= d_{ct}(\log L') d_{ct} + d_x(\log L') dx + d_y(\log L') dy + d_z(\log L') dz \end{aligned}$$

therefore the curvature is

$$\begin{aligned} F &= dA + \frac{1}{2} [A \wedge A] \quad (\because sl(2, \mathbb{C})' \text{ is a real under the conjugate } " = ") \\ &= d((L')^{-1} (d_{ct}(L') \wedge d_{ct} + d_x(L') \wedge dx + d_y(L') \wedge dy + d_z(L') \wedge dz) \\ &\quad + ((L')^{-1} (d_{ct}(L') d_{ct} + d_x(L') dx + d_y(L') dy + d_z(L') dz)) \wedge \\ &\quad ((L')^{-1} (d_{ct}(L') d_{ct} + d_x(L') dx + d_y(L') dy + d_z(L') dz)) \\ &= 0 \end{aligned}$$

and the new factor of the curvature is

$$\begin{aligned} E_t &= d_{ct}((L')^{-1} d_{ct}(L')) + d_x((L')^{-1} d_x(L')) + d_y((L')^{-1} d_y(L')) + d_z((L')^{-1} d_z(L')) \\ &= d_{ct}^2(\log L') + d_x^2(\log L') + d_y^2(\log L') + d_z^2(\log L') \end{aligned}$$

therefore when  $\log L'$  is harmonic then the curvature matrix is zero.

This means that the gravitational field is free, when we have any choice of the gauge group such that  $\log L'$  is harmonic.

If we mention the other word, we must start from the potential and infinitesimal gauge transformation in order to generate the "real" gravitational field.

We base upon above argument and introduce the potential of a particle with gravitational mass  $m_g$  as follows:

$$A = \frac{m_g}{r} \left[ \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} dx + \begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 \\ 0 & 0 & -1 & 0 \end{pmatrix} dy + \begin{pmatrix} 0 & i & 0 & 0 \\ -i & 0 & 0 & 0 \\ 0 & 0 & 0 & -i \\ 0 & 0 & i & 0 \end{pmatrix} dz \right] \in sl(2, \mathbb{C})'$$

and these coefficients of  $dx, dy, dz$  correspond to the infinitesimal Lorentz transformation as

$$\frac{2m_g}{r} \begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \frac{2m_g}{r} \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \text{ and } \frac{2m_g}{r} \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix}$$

because the gravity of a particle carry the x-directional acceleration at the point which separate from the particle to the x-direction and the same for the y, z-direction.

This potential does not satisfy the Yang-Mills' equation (in Corollary 4).

Therefore we take the gauge subgroup  $SL(2, \mathbb{C})' = \begin{pmatrix} a & 0 \\ 0 & E \end{pmatrix}$ ,  $a \in SL(2, \mathbb{C})$  instead of  $SL(2, \mathbb{C})'$ ,

and it acts on the base space as a complex Lorentz transformation  $SO(1, 3, \mathbb{C})$  on the  $\mathbb{C}^{1,3}$  space, i.e.,

$$u \rightarrow u' = au$$

Under the above consideration, we introduce the potential of a particle as follows:

$$A = 1/c \cdot \phi \, d\mathbf{c}t - A_x \, dx - A_y \, dy - A_z \, dz$$

$$= \frac{m_G}{r} \left( \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} dx + \begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} dy + \begin{pmatrix} 0 & i & 0 & 0 \\ -i & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} dz \right) \in \mathfrak{sl}(2, \mathbb{C})''$$

and these coefficients of  $dx, dy, dz$  correspond to the infinitesimal transformations on  $\mathfrak{C}^{1,3}$  as

$$\frac{m_G}{r} \begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & i \\ 0 & 0 & -i & 0 \end{pmatrix}, \frac{m_G}{r} \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -i \\ 1 & 0 & 0 & 0 \\ 0 & i & 0 & 0 \end{pmatrix} \text{ and } \frac{m_G}{r} \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & i & 0 \\ 0 & -i & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix}.$$

Then its curvature  $F$  is

$$E_x = \partial A_x / \partial t - 1/c \cdot \partial \phi / \partial x + \frac{1}{2} c \cdot ([\bar{\phi}, A_x] - [\bar{A}_x, \phi]) = 0$$

$$E_y = \partial A_y / \partial t - 1/c \cdot \partial \phi / \partial y + \frac{1}{2} c \cdot ([\bar{\phi}, A_y] - [\bar{A}_y, \phi]) = 0$$

$$E_z = \partial A_z / \partial t - 1/c \cdot \partial \phi / \partial z + \frac{1}{2} c \cdot ([\bar{\phi}, A_z] - [\bar{A}_z, \phi]) = 0$$

$$B_x = -\partial A_z / \partial y + \partial A_y / \partial z + \frac{1}{2} ([\bar{A}_y, A_z] - [\bar{A}_z, A_y])$$

$$= -\frac{m_G}{r^3} \begin{pmatrix} 0 & z-iy & 0 & 0 \\ z+iy & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$B_y = -\partial A_x / \partial z + \partial A_z / \partial x + \frac{1}{2} ([\bar{A}_z, A_x] - [\bar{A}_x, A_z])$$

$$= -\frac{m_G}{r^3} \begin{pmatrix} -z & ix & 0 & 0 \\ -ix & z & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$B_z = -\partial A_y / \partial x + \partial A_x / \partial y + \frac{1}{2} ([\bar{A}_x, A_y] - [\bar{A}_y, A_x])$$

$$= -\frac{m_G}{r^3} \begin{pmatrix} y & -x & 0 & 0 \\ -x & -y & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

and a new factor is

$$E_t = \partial A_x / \partial x + \partial A_y / \partial y + \partial A_z / \partial z + 1/c \cdot \partial \phi / \partial t$$

$$+ \frac{1}{2} ([\bar{A}_t, A_t] - [\bar{A}_x, A_x] - [\bar{A}_y, A_y] - [\bar{A}_z, A_z])$$

$$= \frac{m_G}{r^3} \begin{pmatrix} x & y+iz & 0 & 0 \\ y-iz & -x & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}.$$

The above curvature and a new factor satisfy the Yang-Mills' equation, i.e.,

$$\rho = \partial E_t / \partial t + (\partial E_x / \partial x + \partial E_y / \partial y + \partial E_z / \partial z)$$

$$+ [\bar{\phi}, E_t] - [\bar{A}_x, E_x] - [\bar{A}_y, E_y] - [\bar{A}_z, E_z]$$

$$= 0$$

$$j_x = (\partial E_x / \partial t + \partial E_t / \partial x) - (\partial B_y / \partial z - \partial B_z / \partial y)$$

$$\begin{aligned}
& + [\bar{\phi}, E_x] - [\bar{A}_x, E_t] - [\bar{A}_y, B_z] + [\bar{A}_z, B_y] \\
& = \frac{3m_G}{r^5} \left( \begin{array}{cc|cc} x^2+y^2+z^2 & xy+ixz-iz-yx & 0 & 0 \\ xy-ixz+izx-yx & -x^2-x^2-z^2 & 0 & 0 \\ \hline 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right) + \frac{m_G}{r^3} \left( \begin{array}{cc|cc} 1+1+1 & 0 & 0 & 0 \\ 0 & -1-1-1 & 0 & 0 \\ \hline 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right) \\
& = 0 \\
j_y & = (\partial E_y / \partial t + \partial E_t / \partial y) - (\partial B_z / \partial x - \partial B_x / \partial z) \\
& + [\bar{\phi}, E_y] + [\bar{A}_x, B_z] - [\bar{A}_y, E_t] - [\bar{A}_z, B_x] \\
& = -\frac{3m_G}{r^5} \left( \begin{array}{cc|cc} yx-xy & x^2iyz+y^2+z^2-izy & 0 & 0 \\ x^2-iyz+y^2+y^2+z^2+izy & -yx+xy & 0 & 0 \\ \hline 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right) + \frac{m_G}{r^3} \left( \begin{array}{cc|cc} 0 & 1+1+1 & 0 & 0 \\ 1+1+1 & 0 & 0 & 0 \\ \hline 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right) \\
& = 0 \\
j_z & = (\partial E_z / \partial t + \partial E_t / \partial z) - (\partial B_x / \partial y - \partial B_y / \partial x) \\
& + [\bar{\phi}, E_z] - [\bar{A}_x, B_y] + [\bar{A}_y, B_x] - [\bar{A}_z, E_t] \\
& = -\frac{3m_G}{r^5} \left( \begin{array}{cc|cc} zx-xz & zy+iz^2-yz+iy^2+ix^2 & 0 & 0 \\ zy-iz^2-yz-iy^2-ix^2 & -zx+xz & 0 & 0 \\ \hline 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right) + \frac{m_G}{r^3} \left( \begin{array}{cc|cc} 0 & i+i+i & 0 & 0 \\ -i-i-i & 0 & 0 & 0 \\ \hline 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right) \\
& = 0 \\
\rho' & = \partial B_x / \partial x + \partial B_y / \partial y + \partial B_z / \partial z + [\bar{\phi}, B_t] - [\bar{A}_x, B_x] - [\bar{A}_y, B_y] - [\bar{A}_z, B_z] = 0 \\
j'_x & = \partial B_x / \partial t + (\partial E_y / \partial z - \partial E_z / \partial y) + [\bar{\phi}, B_x] - [\bar{A}_x, B_t] + [\bar{A}_y, E_z] - [\bar{A}_z, E_y] = 0 \\
j'_y & = \partial B_y / \partial t + (\partial E_z / \partial x - \partial E_x / \partial z) + [\bar{\phi}, B_y] - [\bar{A}_x, E_z] - [\bar{A}_y, B_t] + [\bar{A}_z, E_x] = 0 \\
j'_z & = \partial B_z / \partial t + (\partial E_x / \partial y - \partial E_y / \partial x) + [\bar{\phi}, B_z] + [\bar{A}_x, E_y] - [\bar{A}_y, E_x] - [\bar{A}_z, B_t] = 0.
\end{aligned}$$

Let  $(x^0, x^1, x^2, x^3)$  and  $g_{ij}$  be a generalized coordinates and its metric on the Minkowski space. and  $\Gamma^i{}_{jk}$  be a connection which is torsion free and compatible with the metric  $g_{ij}$ , then the covariant derivative of the vector field  $(u^0, u^1, u^2, u^3)$  is

$$\nabla_j u^i = \partial u^i / \partial x^j + \Gamma^i{}_{jk} u^k$$

moreover when the vector  $(u^i)$  is coincide with  $(dx^i / d\tau)$  which is the velocity of a particle on the world line.

Then

$$\nabla u^i = \partial u^i / \partial x^j \cdot dx^j + \Gamma^i{}_{jk} u^k \cdot dx^j, \quad \nabla u^i / d\tau = 0$$

therefore

$$du^i / d\tau = -\Gamma^i{}_{jk} u^j u^k.$$

This is a equation of motion and the right hand side means 4-dimensional force.

We rewrite the above equation of motion by using of the normal vector  $(u'')$  instead of  $(u')$ , then

$$du'' / d\tau = -\Gamma''{}_{jk} u''^j u''^k, \quad (\Gamma''{}_{jk})_i = (\Gamma^i{}_{jk})_i \in \text{so}(1, 3).$$

We notice that the electromagnetic field (curvature) generate a force and identify the curvature  $G\sigma(E_t), \pm G\sigma(E_x + iB_x), \pm G\sigma(E_y + iB_y), \pm G\sigma(E_z + iB_z)$  as the connection  $(\Gamma''{}_{jk})_0, (\Gamma''{}_{jk})_1, (\Gamma''{}_{jk})_2, (\Gamma''{}_{jk})_3$  and the vector  $(v^i)$  as  $(u'')$ .

For example, let

$$d \begin{pmatrix} v^0 \\ v^1 \\ v^2 \\ v^3 \end{pmatrix} = -G \cdot m_G (\sigma(E_t) dt - \sigma(E_x + iB_x) dx - \sigma(E_y + iB_y) dy - \sigma(E_z + iB_z) dz) \begin{pmatrix} v^0 \\ v^1 \\ v^2 \\ v^3 \end{pmatrix}$$

where  $G$  is a gravitational constant

, i.e.,

$$\begin{aligned} \frac{d}{dt} \begin{pmatrix} v^1 \\ v^2 \\ v^3 \\ v^4 \end{pmatrix} &= \frac{-Gm_G}{r^3} \begin{pmatrix} 0 & x & y & z \\ x & 0 & iz & -iz \\ y & -iz & 0 & ix \\ z & iy & -ix & 0 \end{pmatrix} c + \begin{pmatrix} 0 & 0 & iz & -iy \\ 0 & 0 & y & z \\ iz & -y & 0 & 0 \\ -iy & -z & 0 & 0 \end{pmatrix} \cdot \frac{dx}{dt} + \begin{pmatrix} 0 & -iz & 0 & ix \\ -iz & 0 & -x & 0 \\ 0 & x & 0 & z \\ ix & 0 & -z & 0 \end{pmatrix} \cdot \frac{dy}{dt} \\ &+ \begin{pmatrix} 0 & iy & -ix & 0 \\ iy & 0 & 0 & -x \\ -ix & 0 & 0 & -y \\ 0 & x & y & 0 \end{pmatrix} \cdot \frac{dz}{dt} \cdot \begin{pmatrix} v^1 \\ v^2 \\ v^3 \\ v^4 \end{pmatrix}. \end{aligned}$$

Then

(t-component)

$$\begin{aligned} dv^1/dt &= -Gm_G \cdot r^{-3} \{ (xv^2 + yv^3 + zv^4) c + (izv^3 - iyv^4) x_t + (-izv^2 + ixv^4) y_t + (iyv^2 - ixv^3) z_t \} \\ d/dt \{ c^2 / (c^2 - u^2)^{1/2} \} &= -Gm_G c^2 \cdot r^{-3} (xx_t + yy_t + zz_t) / (c^2 - u^2)^{1/2} \\ &\quad - Gm_G c \cdot r^{-3} \{ (izy_t - iyz_t) x_t + (-izx_t + ixz_t) y_t + (iyx_t - ixy_t) z_t \} / (c^2 - u^2)^{1/2} \\ \frac{1}{2} \cdot c^2 (u^2)_t / (c^2 - u^2)^{3/2} &= -Gm_G c^2 \cdot r^{-2} r_t / (c^2 - u^2)^{1/2} \\ &\quad + iGm_G c \cdot r^{-3} \{ (yz_t - zy_t) x_t + (zx_t - xz_t) y_t + (xy_t - yx_t) z_t \} / (c^2 - u^2)^{1/2} \\ (\mu u^2)_t &= 2Gmm_G (c^2 - u^2) \cdot (1/r)_t \\ (\mu u^2)_t &= 2Gmm_G c^2 \cdot (1/r)_t \quad (\text{when } u \ll 0), \end{aligned}$$

therefore

$$\frac{1}{2} \mu u^2 - Gmm_G c^2 / r = \text{constant}$$

where  $m$  is a mass of another particle.

(x-component)

$$\begin{aligned} dv^2/dt &= -Gm_G \cdot r^{-3} \{ (xv^1 + izv^3 - iyv^4) c + (yv^3 + zv^4) x_t + (-izv^1 - xv^3) y_t + (iyv^1 - xv^4) z_t \} \\ d/dt \{ cx_t / (c^2 - u^2)^{1/2} \} &= -Gm_G \cdot r^{-3} \{ xc^2 + (yy_t + zz_t) x_t - x(y_t)^2 - x(z_t)^2 \} / (c^2 - u^2)^{1/2} \\ &\quad - iGm_G c^2 \cdot r^{-3} \{ (zy_t - yz_t) - zy_t + yz_t \} / (c^2 - u^2)^{1/2} \\ cx_{tt} / (c^2 - u^2)^{1/2} + cx_t u_t / (c^2 - u^2)^{3/2} &= -Gm_G c \cdot r^{-3} \{ xc^2 + (yy_t + zz_t) x_t - x(u^2 - (x_t)^2) \} / (c^2 - u^2)^{1/2} \\ (c^2 - u^2) x_{tt} + x_t u_t &= -Gm_G (c^2 - u^2) \cdot r^{-3} \{ xc^2 + (xx_t + yy_t + zz_t) x_t - xu^2 \} \\ &= -Gm_G (c^2 - u^2)^2 \cdot x r^{-3} - Gm_G (c^2 - u^2) x_t r_t r^{-2}. \end{aligned}$$

(y-component)

$$\begin{aligned} dv^3/dt &= -Gm_G \cdot r^{-3} \{ (yv^1 - izv^2 + ixv^4) c + (izv^1 - yv^2) x_t + (xv^2 + zv^4) y_t + (-ixv^1 - yv^4) z_t \} \\ d/dt \{ cy_t / (c^2 - u^2)^{1/2} \} &= -Gm_G c \cdot r^{-3} \{ yc^2 + (zz_t + xx_t) y_t - y(x_t)^2 - y(z_t)^2 \} / (c^2 - u^2)^{1/2} \\ &\quad - iGm_G c^2 \cdot r^{-3} \{ (-zx_t + xz_t) + zx_t - xz_t \} / (c^2 - u^2)^{1/2} \\ cy_{tt} / (c^2 - u^2)^{1/2} + cy_t u_t / (c^2 - u^2)^{3/2} &= -Gm_G c \cdot r^{-3} \{ yc^2 + (zz_t + xx_t) y_t - y(u^2 - (y_t)^2) \} / (c^2 - u^2)^{1/2} \\ (c^2 - u^2) y_{tt} + y_t u_t &= -Gm_G (c^2 - u^2) \cdot r^{-3} \{ yc^2 + (xx_t + yy_t + zz_t) y_t - yu^2 \} \\ &= -Gm_G (c^2 - u^2)^2 \cdot y r^{-3} - Gm_G (c^2 - u^2) y_t r_t r^{-2}. \end{aligned}$$

(z-component)

$$\begin{aligned} dv^4/dt &= -Gm_G \cdot r^{-3} \{ (zv^1 + iyv^2 - ixv^3) c + (-iyv^1 - zv^2) x_t + (ixv^1 - zv^3) y_t + (xv^2 + yv^3) z_t \} \\ d/dt \{ cz_t / (c^2 - u^2)^{1/2} \} &= -Gm_G c \cdot r^{-3} \{ zc^2 + (xx_t + yy_t) z_t - z(x_t)^2 - z(y_t)^2 \} / (c^2 - u^2)^{1/2} \\ &\quad - iGm_G c^2 \cdot r^{-3} \{ (yx_t - xy_t) - yx_t + xy_t \} / (c^2 - u^2)^{1/2} \end{aligned}$$

$$\begin{aligned} cz_{tt}/(c^2-u^2)^{1/2} + cz_t u_t/(c^2-u^2)^{3/2} &= -Gm_G c \cdot r^{-3} \{zc^2 + (xx_t + yy_t)z_t - z(u^2 - (z_t)^2)\}/(c^2-u^2)^{1/2} \\ (c^2-u^2)z_{tt} + z_t u_t &= -Gm_G (c^2-u^2) \cdot r^{-3} \{zc^2 + (xx_t + yy_t)z_t - zu^2\} \\ &= -Gm_G (c^2-u^2)^2 \cdot zr^{-3} - Gm_G (c^2-u^2)z_t r_t r^{-2}. \end{aligned}$$

The  $x, y, z$ - component formulas are in all

$$\begin{aligned} m(c^2-u^2)x_{tt} + mu_x u_t &= -Gmm_G (c^2-u^2)^2 \cdot xr^{-3} + Gmm_G (c^2-u^2)x_t r_t r^{-2} \\ m(c^2-u^2)y_{tt} + mu_y u_t &= -Gmm_G (c^2-u^2)^2 \cdot yr^{-3} + Gmm_G (c^2-u^2)y_t r_t r^{-2} \\ m(c^2-u^2)z_{tt} + mu_z u_t &= -Gmm_G (c^2-u^2)^2 \cdot zr^{-3} + Gmm_G (c^2-u^2)z_t r_t r^{-2}, \end{aligned}$$

therefore

$$m(c^2-u^2)\alpha + muU_t = -Gmm_G (c^2-u^2)^2 Rr^{-3} - Gmm_G (c^2-u^2)U_t r_t r^{-2}$$

where  $\alpha$  is an acceleration,  $U$  is a velocity,  $R$  is a position vector and each  $a, u, r$  is a length of  $\alpha, U, R$  respectively.

This means that

$$\begin{aligned} m(c^2-u^2)\alpha &= -Gmm_G (c^2-u^2)^2 \cdot Rr^{-3} \therefore \alpha = -Gm_G (c^2-u^2) \cdot Rr^{-3} \\ muu_t &= -Gmm_G (c^2-u^2) \cdot r_t r^{-2} \therefore (u^2)_t = 2Gm_G (c^2-u^2) \cdot (1/r)_t. \end{aligned}$$

hold by comparison with the coefficients of  $U$  and the equation of "t-component".

Eventually, we obtain the Newton's equation of motion and the conservation of energy under the universal gravitation when the speed of another particle is very slow, i.e.,

when  $u \ll 0$ , then

$$m\alpha = -Gmm_G c^2 \cdot Rr^{-3} \quad \text{and} \quad \frac{1}{2} mu^2 - G = \text{constant}.$$

We abbreviate the imaginary component in the first equation by the process of the above calculation.

therefore we obtain the approximate form of Newton's equation as follows :

$$\begin{aligned} d \begin{pmatrix} v^1 \\ v^2 \\ v^3 \\ v^4 \end{pmatrix} \cdot \begin{pmatrix} v^1 \\ v^2 \\ v^3 \\ v^4 \end{pmatrix}^{-1} &= \frac{-Gm_G}{r^3} \left[ \begin{pmatrix} 0 & x & y & z \\ x & 0 & 0 & 0 \\ y & 0 & 0 & 0 \\ z & 0 & 0 & 0 \end{pmatrix} d\mathbf{ct} + \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & y & z \\ 0 & -y & 0 & 0 \\ 0 & -z & 0 & 0 \end{pmatrix} dx + \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & -x & 0 \\ 0 & x & 0 & z \\ 0 & 0 & -z & 0 \end{pmatrix} dy \right. \\ &\quad \left. + \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -x \\ 0 & 0 & 0 & -y \\ 0 & x & y & 0 \end{pmatrix} dz \right]. \end{aligned}$$

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