#### <u>— 重力と電磁気力</u>

The Gravitational Force and the Electromagnetic Force\*

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## Abstract

This paper provides the matrix which contains the gravitation and the electromagnetic field. We explain that the similarity or difference between the gravitation forces and electromagnetic force.

## 1. Introduction

# 1.1. Definition of the imaginary charge and its derivatives

The magnetic charge m is a pure imaginary part of the complex charge as e - im, then its potential (1), magnetic field (2), Maxwell equation (3) and the Coulomb-Lorentz force (4) are

$$\begin{bmatrix} F_t \\ \mathbf{F} \end{bmatrix}^{-} = \begin{bmatrix} -\mathrm{i}E_t \\ \mathbf{E} - \mathrm{i}c\mathbf{B} \end{bmatrix}^{+} \begin{bmatrix} e - \mathrm{i}m \\ \mathbf{0} \end{bmatrix}^{-}, \tag{4}$$

where  $\overline{e - im} = e + im$  means a complex conjugate.

# 1.2. The matrix expression of the mass and its fields like the magnetic charge

It is the same as that of the magnetic charge m. We put the mass M as iM which is a pure imaginary number, because the two masses has the power of absorption. Then its potential (5), (magnetic) field (6), Maxwell equation (7) and the Coulomb-Lorentz force (8) are

$$\begin{bmatrix} \mathbf{i}\phi_g & \\ & -\mathbf{i}\mathbf{A}_g(=\mathbf{0}) \end{bmatrix}^+ = G \begin{bmatrix} \mathbf{i}M & \\ & \mathbf{0} \end{bmatrix}^+ \begin{bmatrix} \mathbf{i}M & \\ & \mathbf{0} \end{bmatrix}^+ \begin{bmatrix} \mathbf{1} & \\ & \mathbf{0} \end{bmatrix}^+ = G \begin{bmatrix} \mathbf{i}\frac{M}{|\mathbf{r}|} & \\ & \mathbf{0} \end{bmatrix}^+$$
(5)

$$\begin{bmatrix} \mathbf{i}B_{gt} \\ \mathbf{E}_{g} - \mathbf{i}\mathbf{c}\mathbf{B}_{g} \end{bmatrix}^{+} = \begin{bmatrix} \partial \mathbf{c}t \\ -\partial \mathbf{r} \end{bmatrix}^{-+} \begin{bmatrix} \mathbf{i} \phi_{g} \\ -\mathbf{i}\mathbf{c}\mathbf{A}_{g} \end{bmatrix}^{+}$$
$$= \begin{bmatrix} \mathbf{i}\frac{\partial \phi_{g}}{\partial \mathbf{c}t} + \mathbf{i}div\mathbf{c}\mathbf{A}_{g} \\ -\mathbf{i}\frac{\partial \mathbf{c}\mathbf{A}_{g}}{\partial \mathbf{c}t} - \mathbf{i}\mathbf{grad}\phi_{g} + \mathbf{rotc}\mathbf{A}_{g} \end{bmatrix}^{+}$$
(6)

$$\begin{bmatrix} \mathbf{i}M \\ \mathbf{0} \end{bmatrix}^{+} = \begin{bmatrix} \partial \mathbf{c}t \\ \partial \mathbf{r} \end{bmatrix}^{+} \begin{bmatrix} \mathbf{i}B_{gt} \\ \mathbf{E}_{g} - \mathbf{i}\mathbf{c}\mathbf{B}_{g} \end{bmatrix}^{+}$$
(7)

$$\begin{bmatrix} F_t \\ \mathbf{F} \end{bmatrix}^{-} = \begin{bmatrix} \mathbf{i}B_{gt} \\ \mathbf{E}_g - \mathbf{i}\mathbf{c}\mathbf{B}_g \end{bmatrix}^{+} \begin{bmatrix} \mathbf{i}M \\ \mathbf{0} \end{bmatrix}^{-}, \text{ this is not } \begin{bmatrix} \mathbf{i}M \\ \mathbf{0} \end{bmatrix}^{-},$$
(8)

where  $\overline{iM} = -iM$  means a complex conjugate.

## 2. The matrix which contained the electric charge and the mass simultaneously

#### 2.1 The electric charge and the mass in the same matrix

We put the electric charge e and the magnetic charge m as  $(e-im)l_t$  which is the time component and the mass  $M(l_x, l_y, l_z)$  which is the space component, which means that the magnetic charge is on the complex conjugate and the mass is on the space conjugate as follows:

$$\vec{(e} - i\vec{m}) + \vec{M} = \begin{bmatrix} k_0(e - im)l_t & & \\ & -GM(l_x, l_y, l_z) \end{bmatrix}^+ \\ = \begin{bmatrix} k_0(e - im) \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \\ & -GM \begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & -i & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -i \\ 1 & 0 & 0 & 0 \\ 0 & i & 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -i \\ 1 & 0 & 0 & 0 \\ 0 & i & 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -i \\ 1 & 0 & 0 & 0 \\ 0 & i & 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -i \\ 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & -i & 0 \\ 0 & -i & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} \end{bmatrix}$$

Then we can use the same standard for each unit of the charge e - im and the mass M. For simplicity, we take the complex charge as q = e - im and "the charge and mass" as  $\vec{q} + \vec{M}$ 

$$= \begin{bmatrix} k_0 q \mathbf{1}_t \\ -GM(\mathbf{1}_x, \mathbf{1}_y, \mathbf{1}_z) \end{bmatrix}^+$$
 And its potential (9), field (10), the Maxwell equation (11) are

$$\left[ \begin{array}{c} \phi_{ge} \\ -\mathbf{c}\mathbf{A}_{ge} \end{array} \right]^{+} = \left[ \begin{array}{c} k_{0}q\mathbf{l}_{t} \\ -GM(\mathbf{l}_{x},\mathbf{l}_{y},\mathbf{l}_{z}) \right]^{+} \left[ \begin{array}{c} \mathbf{l} \\ |\mathbf{r}| \\ \mathbf{0} \end{array} \right]^{+} \\ = \left[ \begin{array}{c} \frac{k_{0}e}{|\mathbf{r}|}\mathbf{l}_{t} \\ -\frac{GM}{|\mathbf{r}|}(\mathbf{l}_{x},\mathbf{l}_{y},\mathbf{l}_{z}) \right]^{+} \\ \left[ \begin{array}{c} gge}{-\mathbf{c}\mathbf{A}_{ge}} \right]^{+} \\ = \left[ \begin{array}{c} \partial \phi_{ge} \\ \partial ct \end{array} + divc\mathbf{A}_{ge} \\ -\frac{\partial c\mathbf{A}_{ge}}{\partial ct} - \mathbf{grad}\phi_{ge} - \mathbf{irotcA}_{ge} \right]^{+} \\ \end{array} \right]$$
(9)

$$\overrightarrow{\mathbf{q}}_{0} + \overrightarrow{\mathbf{M}}_{0} = \begin{bmatrix} q\mathbf{1}_{t} & \\ & -M(\mathbf{1}_{x},\mathbf{1}_{y},\mathbf{1}_{z}) \end{bmatrix}^{+} = \begin{bmatrix} \partial \mathbf{c}t & \\ & \partial \mathbf{r} \end{bmatrix}^{+} \begin{bmatrix} E_{get} & \\ & \mathbf{E}_{ge} - \mathbf{i}\mathbf{c}\mathbf{B}_{ge} \end{bmatrix}^{+}$$
(11)

#### 2.2. Maxwell Equation and the temporary unit

(i) The temporary unit of the electron

By the Coulomb force  $F = \frac{k_0 eq}{r^2}$ , we temporarily define the charge which has the capability to

generate an electric potential as  $e_{w[Cw]}$ ,  $q_{w[Cw]}$  instead of e, q and  $F = \frac{k_0 eq}{r^2} = \frac{e_w q_w}{r^2}$ .

By the equation of motion  $F = m_e \alpha = m_e \frac{d^2 r}{dt^2}$  (Newton), we temporarily define the mass of the

charge which has the difficulty  $m = m_{e[kgi]}$  of moving to the electromagnetic field.

More specifically, the symbol  $e_{w[Cw]}$  is the physical meaning that the quantity  $e_{w[kgw]}$  can accelerate the mass  $m_{e[kgi]}$  by the value  $\frac{d^2r}{dt^2}$ . In this case the units kgi and kg are same and by

the relation 
$$\frac{e_w^2}{1^2} = F_{[kgi \cdot m/s^2]} = \frac{k_{0[kgi \cdot m^3/(C^2 \cdot s^2)]}e^2}{1^2}$$
, we get  $e_{w_{[Cw=kgi^{\frac{1}{2}} \cdot m^{\frac{3}{2}}/s]}} = \sqrt{k_{0[kgi \cdot m^3/(C^2 \cdot s^2)]}}e_{[C]}$ .

(ii) The temporary unit of the mass

By the Universal gravitation of Newton  $F = -\frac{GMm}{r^2}$ , We temporarily define the mass which has the capability to generate a gravitational potential as  $M_{w[kgw]}$ ,  $m_{w[kgw]}$  instead of M, m and

$$F = -\frac{GMm}{r^2} = -\frac{M_w m_w}{r^2}.$$

By the equation of motion  $F = m\alpha = m \frac{d^2 r}{dt^2}$  (Newton) and more we temporarily define the mass of the particle which has the difficulty  $m = m_{i[kgi]}$  of moving to the gravitational field.

More specifically, the symbol  $m_{w[kgw]}$  is the physical meaning that the quantity  $m_{w[kgw]}$  can accelerate the mass  $m_{i[kgi]}$  by the value  $\frac{d^2r}{dt^2}$ . In this case the units kgi and kg are same, and

by the relation  $-\frac{m_w^2}{1^2} = F_{[kgi\cdot m/s^2]} = -\frac{G_{[kgi\cdot m^3/(kg^2\cdot s^2)]}m^2}{1^2}$ , we get  $m_w_{[kgw=kgi^{\frac{1}{2}},m^{\frac{3}{2}}/s]}$ 

$$= \sqrt{G_{[kgi \cdot m^3/(kg^2 \cdot s^2)]}} m_{[kg]}.$$

# 2.3. The Coulomb and the Gravitational Force of "the charge and the mass".

We defined a source 
$$\vec{\mathbf{q}}_w + \vec{\mathbf{M}}_w = \begin{bmatrix} q_w \mathbf{1}_t & & \\ & -M_w (\mathbf{1}_x, \mathbf{1}_y, \mathbf{1}_z) \end{bmatrix}^+$$
, potential  $\begin{bmatrix} \phi_{ge} & & \\ & -c\mathbf{A}_{ge} \end{bmatrix}^+$ , field  $\begin{bmatrix} E_{get} & & \\ & \mathbf{E}_{ge} - ic\mathbf{B}_{ge} \end{bmatrix}^+$  and particle  $\begin{bmatrix} u_{ge0} & & \\ & u_{ge} \end{bmatrix}^- = \begin{bmatrix} q'_w \mathbf{1}_t & & \\ & M'_w (\mathbf{1}_x, \mathbf{1}_y, \mathbf{1}_z) \end{bmatrix}^-$  are as

above 2.1.

Furthermore, we expect the Coulomb and the Gravitational force as

$$\begin{bmatrix} F_t \\ \mathbf{F} \end{bmatrix}^{-} = \begin{bmatrix} E_{get} \\ \mathbf{E}_{ge} - \mathbf{i}\mathbf{c}\mathbf{B}_{ge} \end{bmatrix}^{+} \begin{bmatrix} q'_w \mathbf{1}_t \\ M'_w(\mathbf{1}_x, \mathbf{1}_y, \mathbf{1}_z) \end{bmatrix}^{-}$$
(12)

But this is not the same size matrix. Therefore we take the variation method as follows<sup>1</sup>):

We put 
$$\begin{bmatrix} E \\ c \\ P \end{bmatrix}^{-} = \begin{bmatrix} E_{0} \\ c \\ p \end{bmatrix}^{-} + \begin{bmatrix} \frac{q_{w}}{c} \phi_{ge} \\ \frac{M_{w}}{c} c A_{ge} \end{bmatrix}^{-}$$
 in the previous paper, then  

$$Tr( \begin{bmatrix} \delta ct \\ -\delta r \end{bmatrix}^{+} \begin{pmatrix} \frac{d}{dc\tau} \begin{bmatrix} E \\ c \\ P \end{bmatrix}^{-} - \begin{bmatrix} E_{get} \\ E_{ge} - icB_{ge} \end{bmatrix}^{+} \begin{bmatrix} q_{w}^{+} \frac{u_{ge0}}{c} \\ M_{w}^{+} \frac{u_{ge}}{c} \end{bmatrix}^{-} \end{pmatrix} = 0.$$
(13)

Concretely when the particle is not move, the potential (9) and field (10) are

$$\phi(\vec{\mathbf{q}}, \vec{\mathbf{M}}) = \frac{1}{r}$$

$$\bullet \begin{bmatrix} q_{w} \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \\ \bullet \begin{bmatrix} -M_{w} \begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & -i & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -i \\ 1 & 0 & 0 & 0 \\ 0 & 0 & -i & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -i \\ 1 & 0 & 0 & 0 \\ 0 & -i & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} \end{bmatrix}^{+}$$

$$(14)$$

$$\mathbf{E}(\vec{\mathbf{q}},\vec{\mathbf{M}}) = -\frac{1}{r^{3}}$$

$$\left[ M_{w} \begin{pmatrix} \underline{0} & \underline{x} & \underline{y} & \underline{z} \\ \underline{x} & 0 & \underline{iz} & -\underline{iy} \\ \underline{y} & -\underline{iz} & 0 & \underline{ix} \\ \underline{z} & \underline{iy} & -\underline{ix} & 0 \end{pmatrix} \right]$$

$$\left[ -q_{w} x \begin{pmatrix} \underline{1} & \underline{0} & \underline{0} & \underline{0} \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} + M_{w} \begin{pmatrix} \underline{0} & \underline{0} & \underline{iz} & -\underline{iy} \\ 0 & 0 & y & z \\ \underline{iz} & -y & 0 & 0 \\ -\underline{iy} & -z & 0 & 0 \end{pmatrix} + M_{w} \begin{pmatrix} \underline{1} & \underline{0} & \underline{0} & \underline{0} \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} + M_{w} \begin{pmatrix} \underline{0} & \underline{0} & \underline{iz} & -\underline{iy} \\ 0 & 0 & y & z \\ \underline{iz} & -y & 0 & 0 \\ -\underline{iy} & -z & 0 & 0 \end{pmatrix} + M_{w} \begin{pmatrix} \underline{1} & \underline{0} & \underline{0} & \underline{0} \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} + M_{w} \begin{pmatrix} \underline{0} & \underline{iz} & -\underline{ix} & 0 \\ 0 & x & 0 & z \\ \underline{ix} & 0 & -z & 0 \end{pmatrix} + M_{w} \begin{pmatrix} \underline{0} & \underline{iy} & -\underline{ix} & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} + M_{w} \begin{pmatrix} \underline{0} & \underline{iy} & -\underline{ix} & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} + M_{w} \begin{pmatrix} \underline{0} & \underline{iy} & -\underline{ix} & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} + M_{w} \begin{pmatrix} \underline{0} & \underline{iy} & -\underline{ix} & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} + M_{w} \begin{pmatrix} \underline{0} & \underline{iy} & -\underline{ix} & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} + M_{w} \begin{pmatrix} \underline{0} & \underline{iy} & -\underline{ix} & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} + M_{w} \begin{pmatrix} \underline{0} & \underline{iy} & -\underline{ix} & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} + M_{w} \begin{pmatrix} \underline{0} & \underline{iy} & -\underline{ix} & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} + M_{w} \begin{pmatrix} \underline{0} & \underline{iy} & -\underline{ix} & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} + M_{w} \begin{pmatrix} \underline{0} & \underline{iy} & -\underline{ix} & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} + M_{w} \begin{pmatrix} \underline{0} & \underline{iy} & -\underline{ix} & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} + M_{w} \begin{pmatrix} \underline{0} & \underline{iy} & -\underline{ix} & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} + M_{w} \begin{pmatrix} \underline{0} & \underline{0} & \underline{0} & -\underline{0} \\ 0 & \underline{0} & -\underline{0} \end{pmatrix} + M_{w} \begin{pmatrix} \underline{0} & \underline{0} & \underline{0} & -\underline{0} \\ 0 & \underline{0} & -\underline{0} \end{pmatrix} + M_{w} \begin{pmatrix} \underline{0} & \underline{0} & \underline{0} & -\underline{0} \\ 0 & \underline{0} & -\underline{0} \end{pmatrix} + M_{w} \begin{pmatrix} \underline{0} & \underline{0} & \underline{0} & -\underline{0} \\ 0 & \underline{0} & -\underline{0} \end{pmatrix} + M_{w} \begin{pmatrix} \underline{0} & \underline{0} & -\underline{0} \\ 0 & \underline{0} & -\underline{0} \end{pmatrix} + M_{w} \begin{pmatrix} \underline{0} & \underline{0} & -\underline{0} \\ 0 & \underline{0} & -\underline{0} \end{pmatrix} + M_{w} \begin{pmatrix} \underline{0} & \underline{0} & -\underline{0} \\ 0 & \underline{0} & -\underline{0} \end{pmatrix} + M_{w} \begin{pmatrix} \underline{0} & \underline{0} & -\underline{0} \\ 0 & \underline{0} & -\underline{0} \end{pmatrix} + M_{w} \begin{pmatrix} \underline{0} & \underline{0} & -\underline{0} \\ 0 & \underline{0} & -\underline{0} \end{pmatrix} + M_{w} \begin{pmatrix} \underline{0} & \underline{0} & -\underline{0} \\ 0 & -\underline{0} & -\underline{0} \end{pmatrix} + M_{w} \begin{pmatrix} \underline{0} & \underline{0} & -\underline{0} \\ 0 & -\underline{0} & -\underline{0} \end{pmatrix} + M_{w} \begin{pmatrix} \underline{0} & -\underline{0} & -\underline{0} \\ -\underline{0} & -\underline{0} \end{pmatrix} + M_{w} \begin{pmatrix} \underline{0} & -\underline{0}$$

Additionally, we calculate the above trace (13).

(i) When  $\delta \mathbf{r} = 0$  (time component)

$$Tr(\frac{\mathrm{d}\frac{E}{\mathrm{c}}}{\mathrm{d}\mathrm{c}\tau}) = Tr(\{E_{get}: q'_{w}, \frac{u_{ge0}}{\mathrm{c}} + (\mathbf{E}_{ge} - \mathrm{ic}\,\mathbf{B}_{ge}) \bullet M'_{w}, \frac{\mathbf{u}_{ge}}{\mathrm{c}}\}) = 0$$

(ii) When  $\delta ct = 0$  (space component)

$$Tr(\frac{\mathrm{d}\mathbf{P}}{\mathrm{d}\mathrm{c}\tau}) = Tr(E_{get} \cdot M'_{w} \frac{\mathbf{u}_{ge}}{\mathrm{c}} + (\mathbf{E}_{ge} - \mathrm{i}\mathrm{c}\mathbf{B}_{ge}) \cdot q'_{w} \frac{u_{ge0}}{\mathrm{c}} - \mathrm{i}(\mathbf{E}_{ge} - \mathrm{i}\mathrm{c}\mathbf{B}_{ge}) \times M'_{w} \frac{\mathbf{u}_{ge}}{\mathrm{c}}$$

For simplicity we limit the x-direction.

The charge and the mass is 
$$\overrightarrow{\mathbf{q}}_{w} + \overrightarrow{\mathbf{M}}_{w} = \begin{bmatrix} q_{w} \mathbf{1}_{t} & & \\ -M_{w}(\mathbf{1}_{x}, \mathbf{1}_{y}, \mathbf{1}_{z}) \end{bmatrix}^{+}$$
  

$$= \begin{bmatrix} q_{w} \begin{pmatrix} \underline{1} & \underline{0} & \underline{0} & \underline{0} \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \\ -M_{w} \begin{pmatrix} (\underline{0} & \underline{1} & \underline{0} & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & i \\ 0 & 0 & -i & 0 \end{pmatrix}, \begin{pmatrix} \underline{0} & \underline{0} & \underline{1} & \underline{0} \\ 0 & 0 & 0 & -i \\ 1 & 0 & 0 & 0 \\ 0 & i & 0 & 0 \end{pmatrix}, \begin{pmatrix} \underline{0} & \underline{0} & \underline{0} & \underline{1} \\ 0 & 0 & i & 0 \\ 0 & -i & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix}, \begin{bmatrix} \underline{0} & \underline{0} & \underline{1} & \underline{0} \\ 0 & 0 & -i & 0 \\ 0 & 0 & -i & 0 \end{pmatrix}, \begin{pmatrix} \underline{0} & \underline{0} & \underline{0} & \underline{1} \\ 0 & 0 & i & 0 \\ 0 & -i & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} \end{bmatrix}$$

And the electric and the gravitational field is  $\ E(q,M)$ 

$$= -\frac{1}{r^{3}} \begin{bmatrix} M_{w} \begin{pmatrix} \underline{0} & \underline{x} & \underline{0} & \underline{0} \\ \underline{x} & 0 & 0 & 0 \\ 0 & 0 & 0 & ix \\ 0 & 0 & -ix & 0 \end{pmatrix} \\ & & & & \\ & & &$$

Therefore we calculate the trace

$$Tr( \begin{bmatrix} \delta \mathbf{c}t & \\ & -\delta \mathbf{r} \end{bmatrix}^{+} \begin{bmatrix} E_{get} & \\ & \mathbf{E}_{ge} - \mathbf{i}\mathbf{c}\mathbf{B}_{ge} \end{bmatrix}^{+} \begin{bmatrix} q'_{w} \frac{u_{ge0}}{\mathbf{c}} & \\ & M'_{w} \frac{\mathbf{u}_{ge}}{\mathbf{c}} \end{bmatrix}^{-} ) = \mathbf{0} \cdot$$

(The time component)

$$F_{t} = Tr(\frac{\mathrm{d}\frac{E}{\mathrm{c}}}{\mathrm{d}\mathrm{c}\tau}) = Tr(E_{get} \cdot q'_{w} \frac{u_{ge0}}{\mathrm{c}} + (\mathbf{E}_{ge} - \mathrm{ic} \mathbf{B}_{ge}) \cdot M'_{w} \frac{\mathbf{u}_{ge}}{\mathrm{c}}) = 0 \cdot$$

(The space component)

$$\mathbf{F} = Tr(\frac{d\mathbf{P}}{dc\tau}) = Tr(\underbrace{E_{get}}{M'_w} \frac{\mathbf{u}_{ge}}{c} + (\underbrace{\mathbf{E}_{ge}}{-ic\mathbf{B}_{ge}}) \cdot q'_w \frac{u_{ge0}}{c} - i(\underbrace{\mathbf{E}_{ge}}{-ic\mathbf{B}_{ge}}) \times M'_w \frac{u_{ge0}}{c},$$

where

$$Tr(\underbrace{E_{get} \cdot M'_{w} \frac{\mathbf{u}_{gex}}{\mathbf{c}}}_{\mathbf{c}}) = Tr(\frac{-M_{w}M'_{w}}{\mathbf{c}} \begin{pmatrix} \underline{0} & \underline{x} & \underline{0} & 0\\ x & 0 & 0 & 0\\ 0 & 0 & 0 & ix\\ 0 & 0 & -ix & 0 \end{pmatrix} \begin{pmatrix} \underline{0} & \underline{1} & \underline{0} & 0\\ 1 & 0 & 0 & 0\\ 0 & 0 & 0 & i\\ 0 & 0 & -i & 0 \end{pmatrix} = -4 \frac{M_{w}M'_{w}}{\mathbf{c}} x ,$$

$$Tr(\underbrace{(\mathbf{E}_{ge} - \mathbf{ic}\mathbf{B}_{ge})_{x} \cdot q'_{w} \frac{u_{ge0}}{\mathbf{c}}}_{\mathbf{c}}) = Tr(\frac{q_{w}q'_{w}}{\mathbf{c}} \begin{pmatrix} \underline{x} & \underline{0} & \underline{0} & \underline{0}\\ 0 & x & 0 & 0\\ 0 & 0 & x & 0\\ 0 & 0 & 0 & x \end{pmatrix} \begin{pmatrix} \underline{1} & \underline{0} & \underline{0} & \underline{0}\\ 0 & 1 & 0 & 0\\ 0 & 0 & 1 & 0\\ 0 & 0 & 0 & x \end{pmatrix} = 4 \frac{q_{w}q'_{w}}{\mathbf{c}} x ,$$

$$Tr(-i(\mathbf{E}_{ge} - ic\mathbf{B}_{ge}) \times M'_{w} \frac{\mathbf{u}_{ge}}{c})$$

$$= Tr(i\frac{M_{w}M'_{w}}{c} \begin{pmatrix} 0 & 0 & 0 & ix \\ 0 & 0 & -x & 0 \\ 0 & x & 0 & 0 \\ ix & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & i & 0 \\ 0 & -i & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} - i\frac{M_{w}M'_{w}}{c} \begin{pmatrix} 0 & 0 & -ix & 0 \\ 0 & 0 & 0 & -x \\ -ix & 0 & 0 & 0 \\ 0 & x & 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -i \\ 1 & 0 & 0 & 0 \\ 0 & i & 0 & 0 \end{pmatrix}$$

$$= -4\frac{M_{w}M'_{w}}{c}x - 4\frac{M_{w}M'_{w}}{c}x.$$

Therefore the space component

$$\mathbf{F} = Tr(\frac{d\mathbf{P}}{dc\tau}) = Tr(E_{get} \cdot M'_w \frac{\mathbf{u}_{ge}}{c} + (\mathbf{E}_{ge} - ic\mathbf{B}_{ge}) \cdot q'_w \frac{u_{ge0}}{c} - i(\mathbf{E}_{ge} - ic\mathbf{B}_{ge}) \times M'_w \frac{\mathbf{u}_{ge}}{c}) = 4(\frac{q_w q'_w}{c} - \frac{3}{2}\frac{M_w M'_w}{c})$$

As a result, this shows that the universal gravitation has 3 times as the much relation as electromagnetic power; we think that this reason is that the time is one-direction and the space is a three-direction.

#### 3. The planet and atom

### 3.1. Angular momentum

The hypothesis about electron arrangement (orbit).

"<u>The electron which is not excited is arranged one by one so that it may become a fixed angular</u> momentum (the amount of resonance)."

# Example 1 (Hydrogen nucleus H) the ionization energy is $E_H = 13.598 eV$

We put the circular orbit radius  $r_1$  of the electron which is not excited. Then the speed is

$$\frac{v_1}{c} = \sqrt{\frac{R_0}{r_1}} \left( = \sqrt{\frac{k_0 e^2}{m_e c^2 r_1}} \right) \text{ by the balance equation } r_1 \left(\frac{v_1}{c}\right)^2 = R_0 \left( = \frac{k_0 e^2}{m_e c^2} \right). \text{ Therefore the momentum}$$
  
is  $m_e r_1 v_1 = m_e c \sqrt{r_1 R_0} \left( = \sqrt{m_e r_1 k_0 e^2} = \frac{h}{2\pi} = \hbar \right) \text{ where } \hbar = 1.05457 \times 10^{-34} \text{ } [kg \cdot m^2 / s].$ 

Example 2 (Helium nucleus  $He^+$ ) the ionization energy is  $E_{He^+} = 54.416eV(=E_H \times 4)$ 

We put the circular orbit radius  $r_1' = \frac{r_1}{2}$ ,  $R_0' = 2R_0$  of the electron which is not excited. Then

the speed is  $\frac{v_1'}{c} = \sqrt{\frac{R_0'}{r_1'}} = 2\sqrt{\frac{R_0}{r_1}} = \frac{\frac{2}{c}v_1}{c}$  by the balance equation  $r_1'(\frac{v_1'}{c})^2 = R_0'(=\frac{2k_0e^2}{m_ec^2})$ 

 $=2R_0$ .

Therefore the momentum is  $m_e r_1 v_1' = m_e \frac{r_1}{2} (2v_1) = m_e r_1 v_1 (= \hbar)$ .

**Example 3** (Lithium atom core  $Li^{2+}$ ) the ionization energy is  $E_{Li^{2+}} = 122.451 eV(=E_H \times 9)$ 

We put the circular orbit radius  $r_1 = \frac{r_1}{3}$ ,  $R_0 = 3R_0$  of the electron which is not excited. Then

the speed is 
$$\frac{v_1}{c} = \sqrt{\frac{R_0}{r_1}} = 3\sqrt{\frac{R_0}{r_1}} = \frac{3v_1}{c}$$
 by the balance equation  $r_1 \left(\frac{v_1}{c}\right)^2 = R_0 \left(\frac{3k_0e^2}{m_ec^2}\right)$ 

 $= 3R_0$ .

Therefore the momentum is  $m_e r_1 "v_1" = m_e \frac{r_1}{3} (3v_1) = m_e r_1 v_1 (=\hbar)$ .

Moreover, it can be concluded that the point  $\frac{r_1}{n}$  of resonating according to the strength of an electric field is near in inverse proportion to the number n of the protons in a core. Thereby, a hypothesis can be prepared, saying, "The angular momentum of non-excited electron is constant which was not depended on the number n of the protons in a core."

#### 3.1.1. The electron around the atomic nucleus

Here, we define the resonance value  $k = \frac{m_e r_1 v_1}{e_{[C]}} \approx 6.58205 \times 10^{-16} {}_{[kg \cdot m^2/(C^2 \cdot s)]}$  as the point of the resonance instead of angular momentum  $\hbar = m_e r_1 v_1$  in the hydrogen atom, moreover this resembles the resonance of the whistle, and the resonating point becomes near in proportion to the value of a central electric charge q.

#### 3.1.2. The planet and the satellite for solar system

In the case of the planet which goes around the Sun, the resonating point becomes far in proportion to the mass M of a central star, therefore we define the resonance value  $K_s = \frac{m_i r_1 v_1}{m \cdot M_{[m^2/(kg \cdot s)]}}$  (where m is the mass and  $m_i$  is the inertial mass), as the point of the resonance instead of angular momentum, moreover this resembles the relation of the size and pitch

of a drum.

#### 3.1.3. The calculation for the resonance value K

It takes into consideration that universal gravitation has 3 times as much relation as electromagnetic power in the last of the section 2. We take a standard value of the resonance  $K_s = 3_{[C^2/kg^2]} \times k = 1.97461 \times 10^{-15}_{[m^2/(kg s)]}$ in the planet and each point of the resonance is measured as follows:

**Example 4** The resonance value  $K_0 = \frac{rv}{M}$  of the planet around the Sun

We calculate the resonance values of the Venus, the Earth and the Mars as follows;

(i) The orbital speed of the Venus is  $v = 3.5020 \times 10^{4}_{[m/s]}$  and the distance between the Venus and the Sun is  $r = 1.08204 \times 10^{11}_{[m]}$ .

Then we get the value  $K_0 = \frac{rv}{M_{[kg]}} = 1.90516 \times 10^{-15} {}_{[m^2/(kg \cdot s)]}.$ 

(ii) The orbital speed of the Earth is  $v = 2.9783 \times 10^4_{[m/s]}$  and the distance between the Earth and the Sun is  $r = 1.49598 \times 10^{11}_{[m]}$ . Then we get the value  $K_0 = \frac{rv}{M_{[kg]}} = 2.24013 \times 10^{-15}_{[m^2/(kg \cdot s)]}$ .

(iii) The orbital speed of the Mars is  $v = 2.4128 \times 10^4_{[m/s]}$  and the distance between the Mars and

the Sun is  $r = 2.27942 \times 10^{11} [m]$ . Then we get the value  $K_0 = \frac{rv}{M_{[kg]}} = 2.76518 \times 10^{-15} [m^2/(kg \cdot s)]$ .

By (1), (2) and (3), the standard value of the resonance  $K_s = 1.97461 \times 10^{-15} [m^2/(kg \cdot s)]$  is between the Venus and the Earth.

In order to take out a better point, although there is no basis in particular. But we take the value

$$K_m(=mean) = \frac{\frac{Venus + Earth}{2} + Mars}{2} = 2.42 \times 10^{-15} \text{ (no reason)}, \quad r_1 = K_m^{-2} \frac{M}{G} ,$$

$$v_1 = \frac{G}{K_m}$$
 as a point of the resonance.

This formula is no reason, but this is near the value  $2.23 \times 10^{-15}_{[m^2/(kg \cdot s)]}$  by a method of least squares to resonance among Jupiter to Pluto. Therefore we get the next table 1.

## Table 1

Ratio of the resonance point for the planet.

	Mercury	(mean)	Jupiter	Saturn	Uranus	Neptune	Pluto
Orbital radius[m]	5.79E+10	(1.75E+11)	7.78E+11	1.43E+12	2.88E+12	4.50E+12	5.92E+12
Orbital speed [m/s]	4.79E+04	(2.76E+04)	1.31E+04	9.64E+03	6.79E+03	5.43E+03	4.74E+03
Resonance $[m^2/(kg \cdot s)]$	1.39E-15	2.42E-15	5.11E-15	6.92E-15	9.82E-15	1.23E-14	1.41E-14
Ratio of resonance	0.58	1	2.11	2.86	4.06	5.08	5.82

The value of the set (Venus, Earth, Mars) is 1, then the value of Jupiter , Saturn, Uranus, Neptune ,Pluto is about 2, 3, 4, 5, 6 respectively.

We compare two resonance value the mean value and the standard value, and its ratio is

$$R(=\frac{m}{m_i}) = \frac{mean}{K_s} = \frac{2.42 \times 10^{-15}}{1.97 \times 10^{-15}} = 1.225_{[-]}.$$

This is equivalent to having estimated the weight of the central star R times greatly. And the mercury is very closed to the Sun, therefore its orbit is elliptic and its rotation is affected in revolution.

# Example 5 The resonance value $K_0 = \frac{rv}{M}$ of the satellite around the planet

We calculate the resonance values of a satellite around the planet as follows;

By two formula  $K = \frac{r_1 v_1}{M}$  (resonance) and  $r_1 v_1^2 = GM$  (balance equation in the circle orbit), we

get the expected the minimum orbital radius of the satellite  $r_{1[m]} = K^2_{[m^4/(kg^2 \cdot s^2)]} \frac{M_{[kg]}}{G_{[m^3/(kg \cdot s)]}}$ .

For example, the case of the Earth and the moon, the orbital radius of the moon is  $3.84 \times 10^8$  m, the orbital speed is  $1.018 \times 10^3$  m/s and the Earth mass is  $5.977 \times 10^{24}$  kg. Therefore the position of the satellite expected is  $r_1 = K^2 \frac{\underline{R} \cdot M}{G} \div 4.27614 \times 10^5 m$ , where the mass of the central star is being

corrected in R double here. This value  $r_1 = 4.27614 \times 10^5 m$  means that it's inside the equatorial radius 6378000 m of the Earth. At other planets, the expected radius  $r_1$  is inside the equatorial

radius except for Jupiter only.

The ratio of the resonance point can change by the square root of the radius, because

$$K = \frac{r_1 v_1}{R \cdot M} = \frac{r_1}{R \cdot M} \sqrt{\frac{GR \cdot M}{r_1}} = \sqrt{\frac{r_1 G}{R \cdot M}}$$
. Therefore we get the next table 2.

# Table 2

Square root of ratio of the radius for the planet.

	Earth	Jupiter	Saturn	Uranus	Neptune	Pluto
Mass[10^24kg]	5.977	1899	568.8	86.67	103	0.012
Expected r1[m]	4.28E+05	1.36E+08	4.07E+07	6.20E+06	7.37E+06	8.59E+02
Equatorial radius[m]	6.38E+06	7.15E+07	6.03E+07	2.56E+07	2.48E+07	1.14E+06
Stationary orbit[m]	4.22E+07	1.59E+08	1.09E+08	8.47E+07	9.37E+07	1.84E+07
Proximity	3.84E+08	1.28E+08	1.34E+08	4.98E+07	4.82E+07	1.96E+08
radius <b>r0</b> [m]	(Moon)	(Metis∼)	(Pan~)	(Cordelia $\sim$ )	(Naiad $\sim$ )	(Charon $\sim$ )
$\sqrt{r_{r1}^0}$	29.97	0.97-14.92	1.81-24.54	2.83-58.06	2.56(?)-81.03	150.94-274.61

# 4. Conclusion

The gravity force is very similar to the electronic force but has 3 times power. The planet arrangement is similar to the electron arrangement but is little influenced by its inner planet.

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